



Selex ES/Academic Collaboration in SAR-MTI: Using PicoSAR in Research to get to the Real World Faster

Stuart Kennedy

*UDRC Industrial Day
Heriot-Watt University, Friday 27th June 2014*



- ✦ Engineering Doctorate student at The University of Edinburgh with Prof Bernie Mulgrew
- ✦ Based full-time with Selex ES as Industrial Sponsor
- ✦ Supported by EPSRC
- ✦ Additional support from the Royal Commission for the Exhibition of 1851
- ✦ Research topic:
“Slow-moving target detection in SAR”
- ✦ Perfectly suited for industrial/academic collaboration



- ✦ Engineering Doctorate as a vehicle for collaboration
 - What is an EngD?
 - What advantageous does it offer?

- ✦ Brief introduction to moving objects in Synthetic Aperture Radar

- ✦ Radar trials data with PicoSAR

- ✦ Case study: Slow-moving SAR-MTI
 - How industry is essential
 - Adaptive channel alignment for clutter cancellation
 - PD-STAP
 - Detection by focusing

Engineering Doctorate

- ✦ PhD-equivalent research in industry with commercial focus
 - ✦ Focus on practical applications and implementation
 - ✦ Examined differently with less focus on publications and novelty
 - ✦ Additional taught element including part-MBA
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- ✦ Flexibility and research-focus of academia
 - ✦ Practical experience and resources of industry



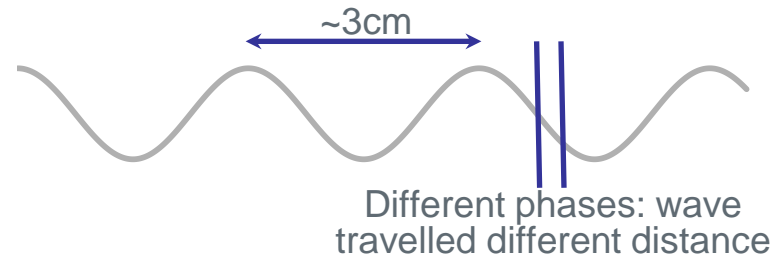
An Aside: Royal Commission for the Exhibition of 1851

- ✧ Victoria and Albert's Great Exhibition of 1851
 - Crystal palace
 - “Confirm Great Britain's position in the world”
- ✧ Great success
 - 6 million visitors, £21m profit (inflation adjusted)
- ✧ Charged by royal charter with:
 - “increasing the means of industrial education and extending the influence of science and art upon productive industry”**
- ✧ Bought land in Kensington
- ✧ Now award £2m each year
- ✧ Nobel laureates:
 - John Cockcroft
 - Alexander Todd
 - Ernest Rutherford
 - John Cornforth
 - Peter Higgs

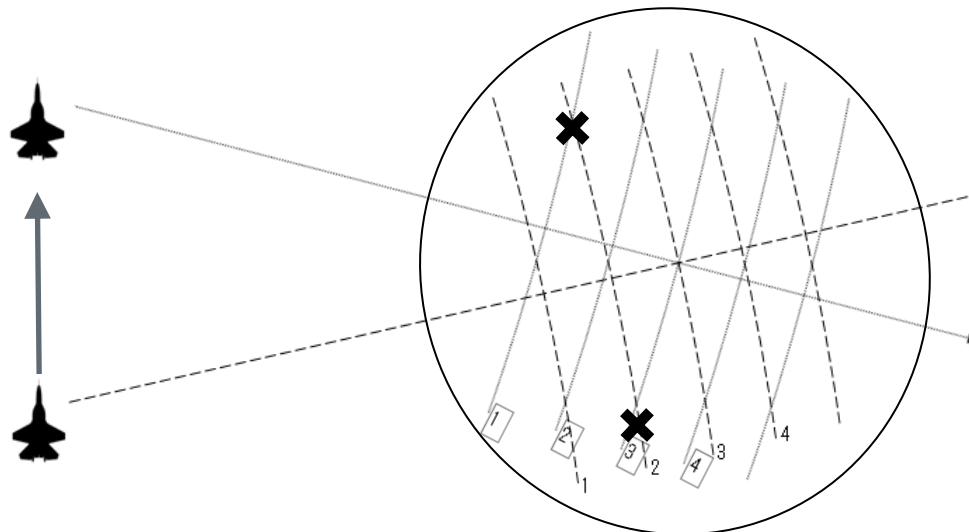


Synthetic Aperture Radar

- ✦ Synthesises a huge aperture utilising the aircraft motion
 - Bigger aperture = better azimuth resolution
- ✦ Each pulse gives a slightly different range measurement from phase

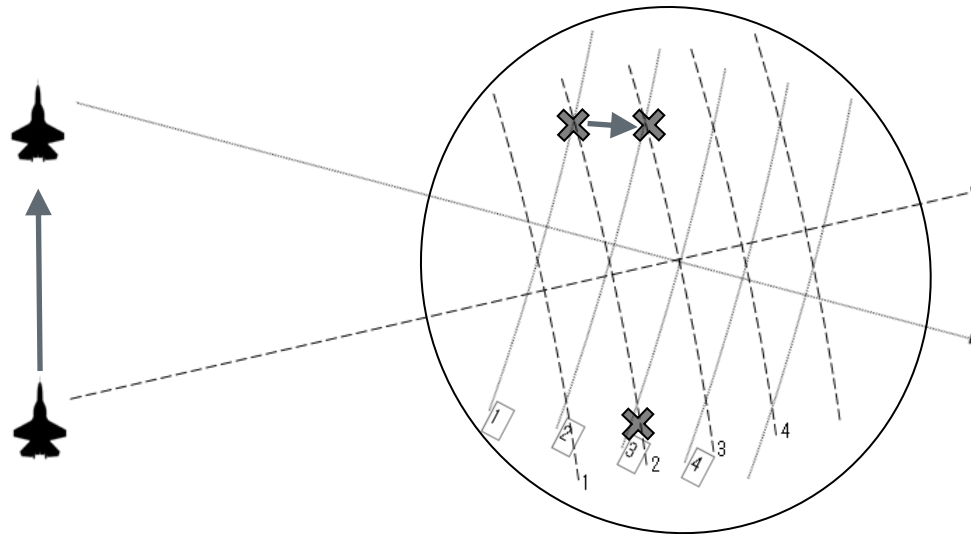


- ✦ Reflectors further from the scene centre move more between pulses



Moving Targets in SAR

- ✦ Moving targets have a different change in distance
- ✦ SAR processing images as if everything is stationary

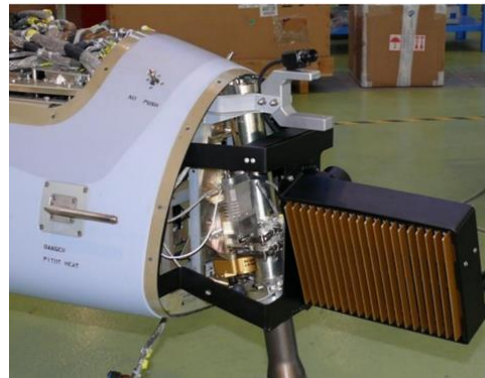
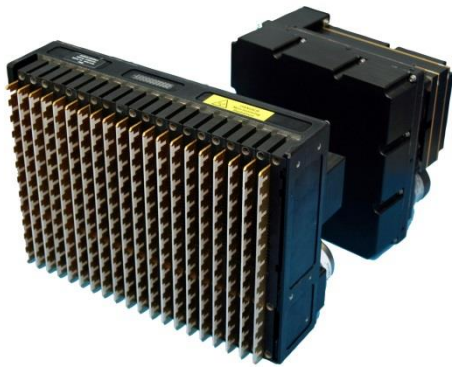


- ✦ So moving targets are imaged in the wrong place
- ✦ Displacement is proportional to velocity (position from Doppler)
- ✦ Varying velocity gives varying displacement (a smear)

- ✦ Phase difference between two separate spatial channels gives independent (Doppler-free) measurement of angle

PicoSAR

Lightweight, low-cost AESA system



- ✦ Low-cost system
- ✦ Lightweight at only 10kg
- ✦ **Dual-channel** capabilities
- ✦ On-board inertial navigation
- ✦ On-board image formation
- ✦ Data storage

Example Trials Scenario

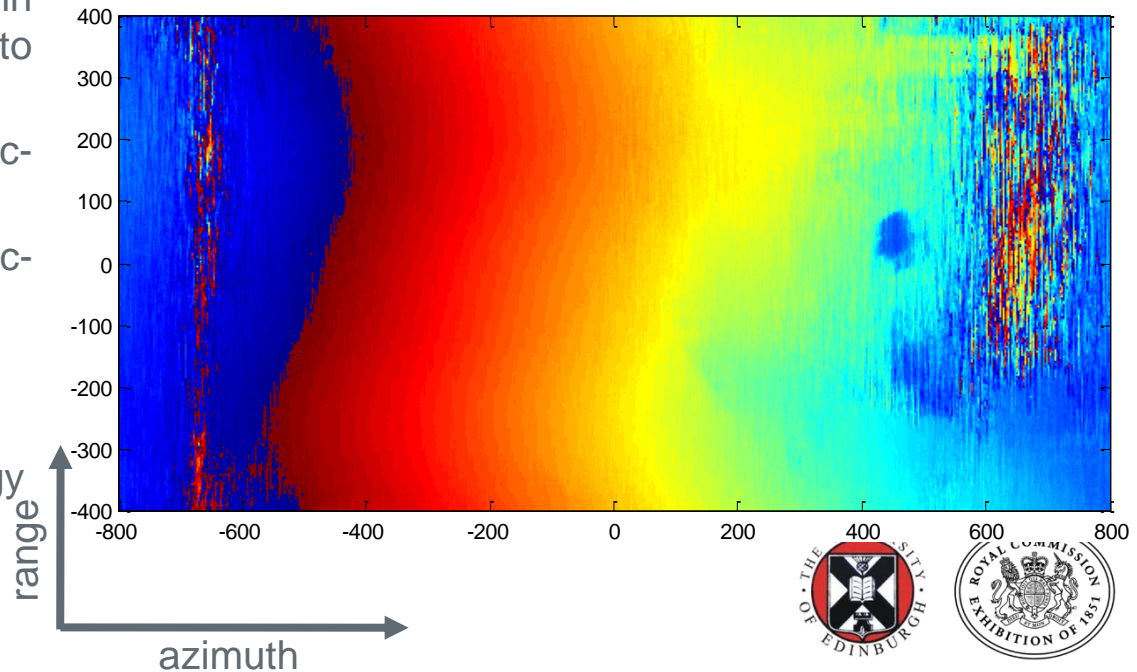
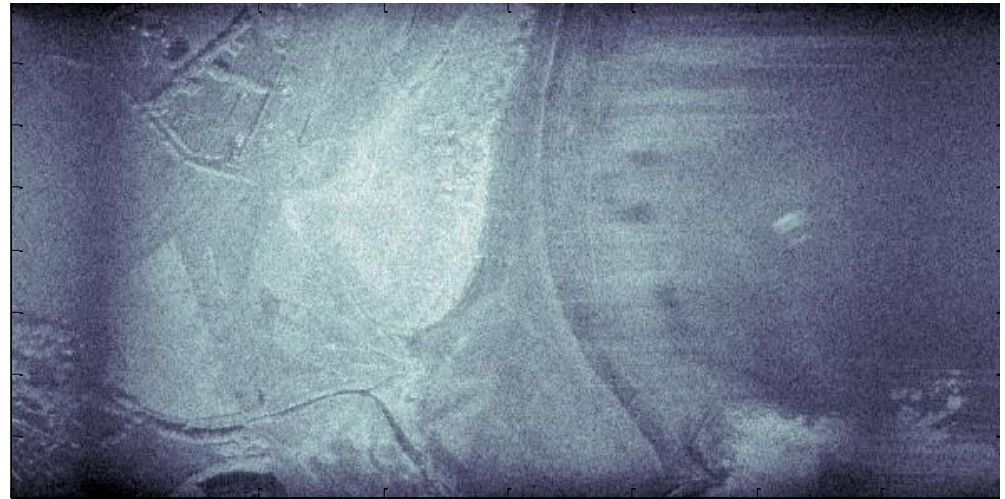
- ✦ PicoSAR mounted on helicopter
- ✦ Beach scene
- ✦ Walking targets with ground-truth
 - No RCS enhancement
- ✦ Varied clutter
 - Sea, sand, grass, buildings
- ✦ Matlab processing



Adaptive Channel Alignment (ACA)

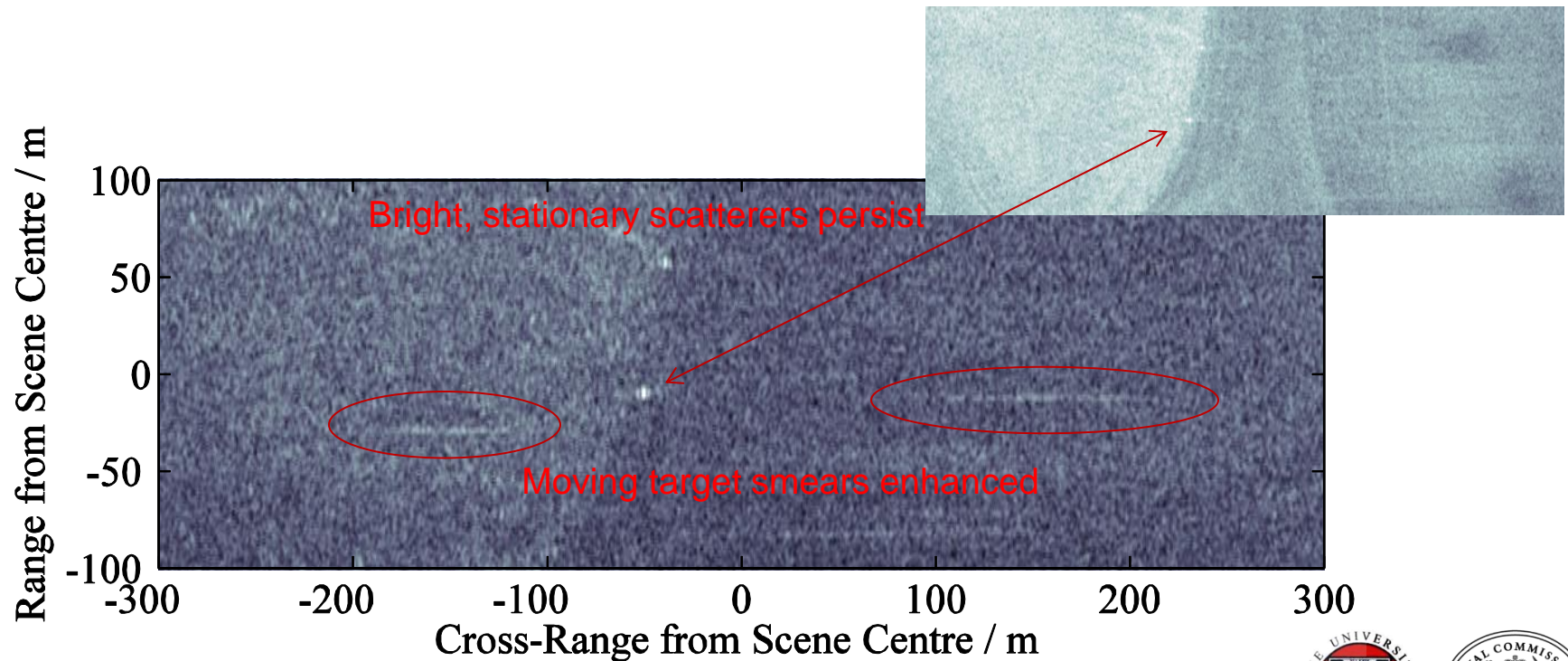
Channel Calibration

- ✦ Channels have to be aligned
- ✦ The necessary phase delay can be determined from geometry
 - Needs additional calibration
- ✦ OR: adaptively measure delay from images
 - Implicitly handles calibration and many other errors
- ✦ Determine correlation in neighbouring range gates to estimate phase difference
 - Smooth variation is included in measurement
 - Sharp variation is not included
- ✦ Offset due to mismatch
- ✦ Linear variation due to DoA
- ✦ Additional pattern from topology



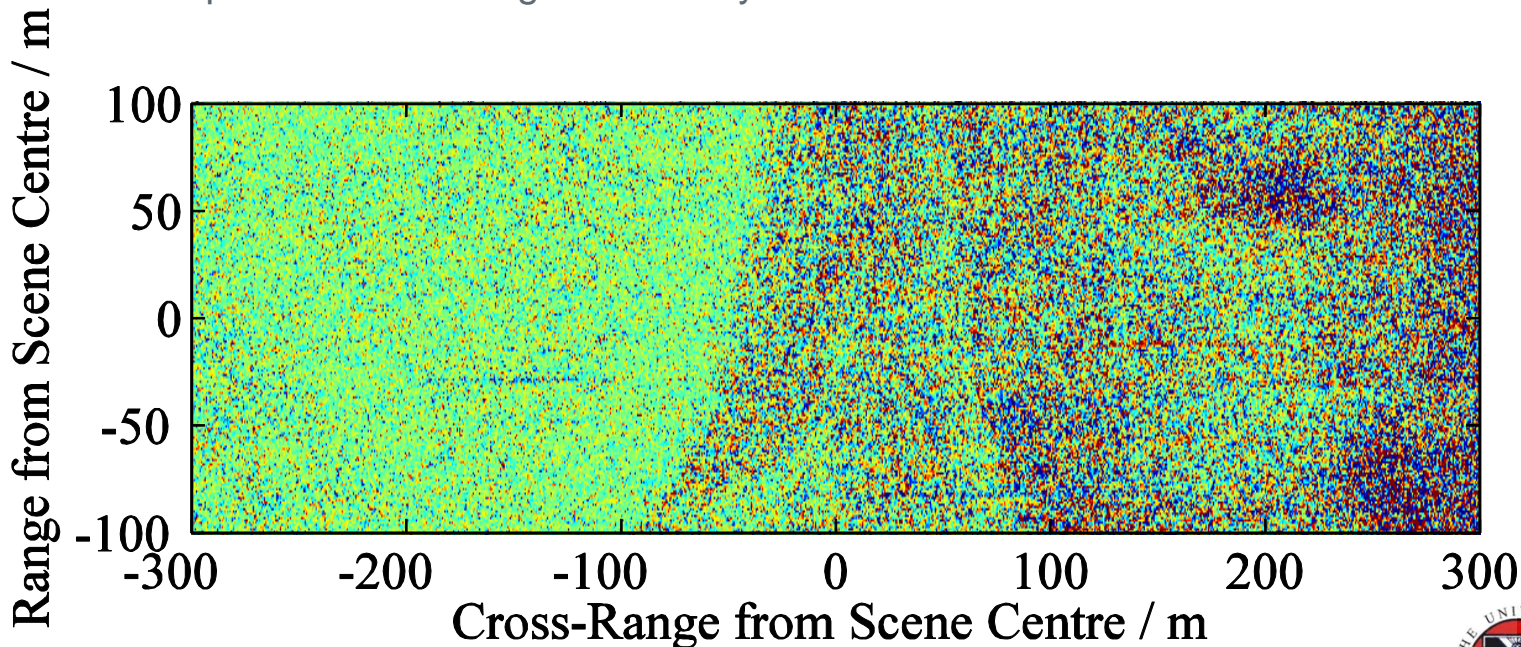
Displaced Phase-Centre Antenna (DPCA)

- ✦ Subtracts channels
- ✦ Traditionally: Arrange PRF so that trailing antenna mimics position of the lead antenna on the previous pulse
- ✦ Or: Phase delay can be introduced to remove the hardware constraint
- ✦ ACA far superior to derivation of delay from geometry



Along-Track Interferometry (ATI)

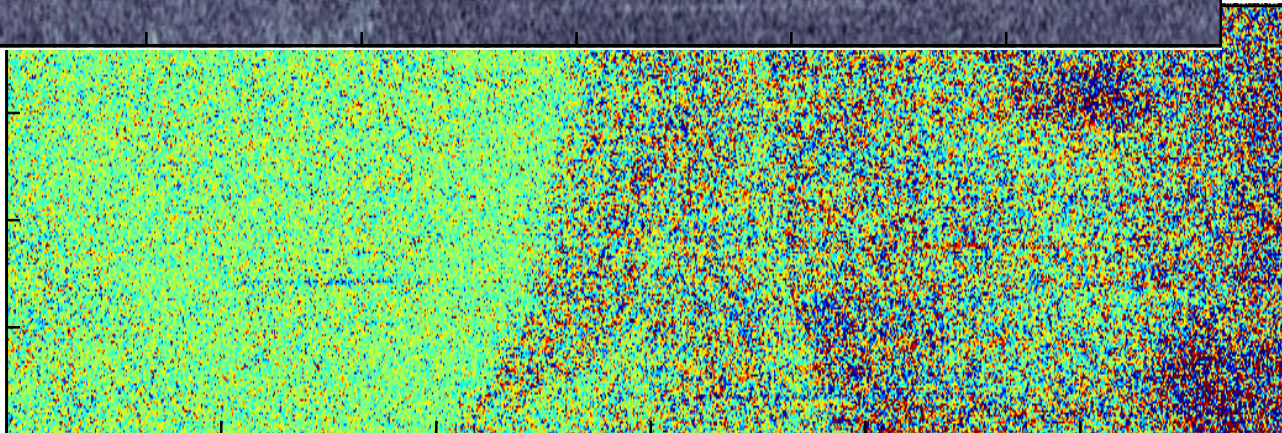
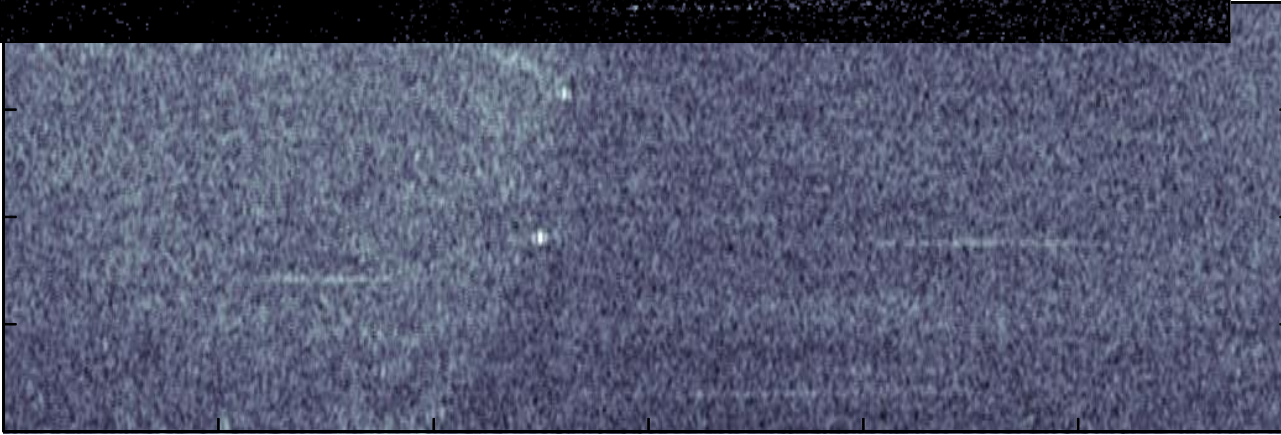
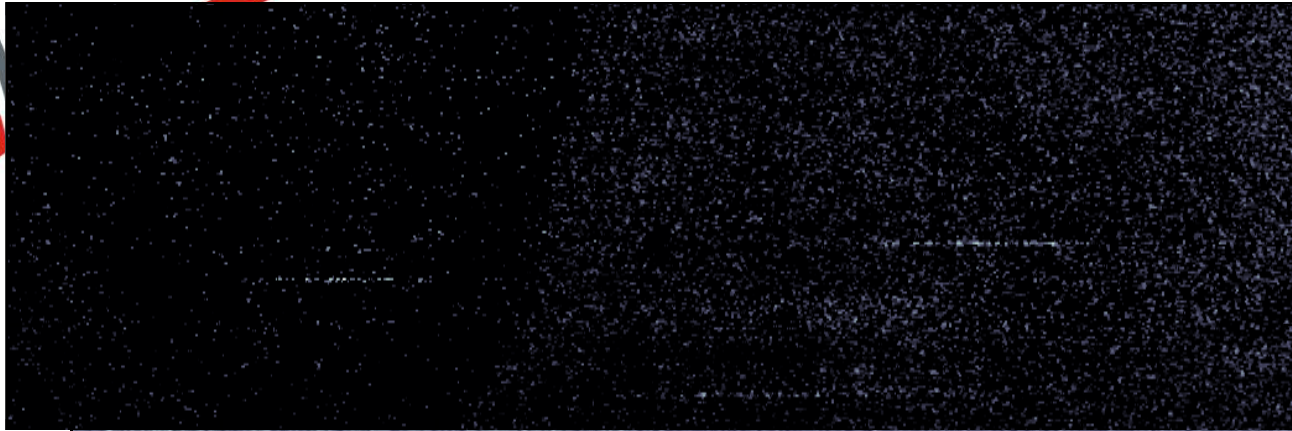
- ✦ Calculates the phase difference between two aligned channels through conjugate multiplication
- ✦ Phase difference gives true azimuth position from which velocity can be derived
 - Although this can be corrupted by coincident clutter
- ✦ Improved by ACA
- ✦ Poor performance in dark areas due to dominance of phase noise
- ✦ No problems from bright stationary scatterers



Hybrid DPCA/ATI Combination

The Perfect Blend

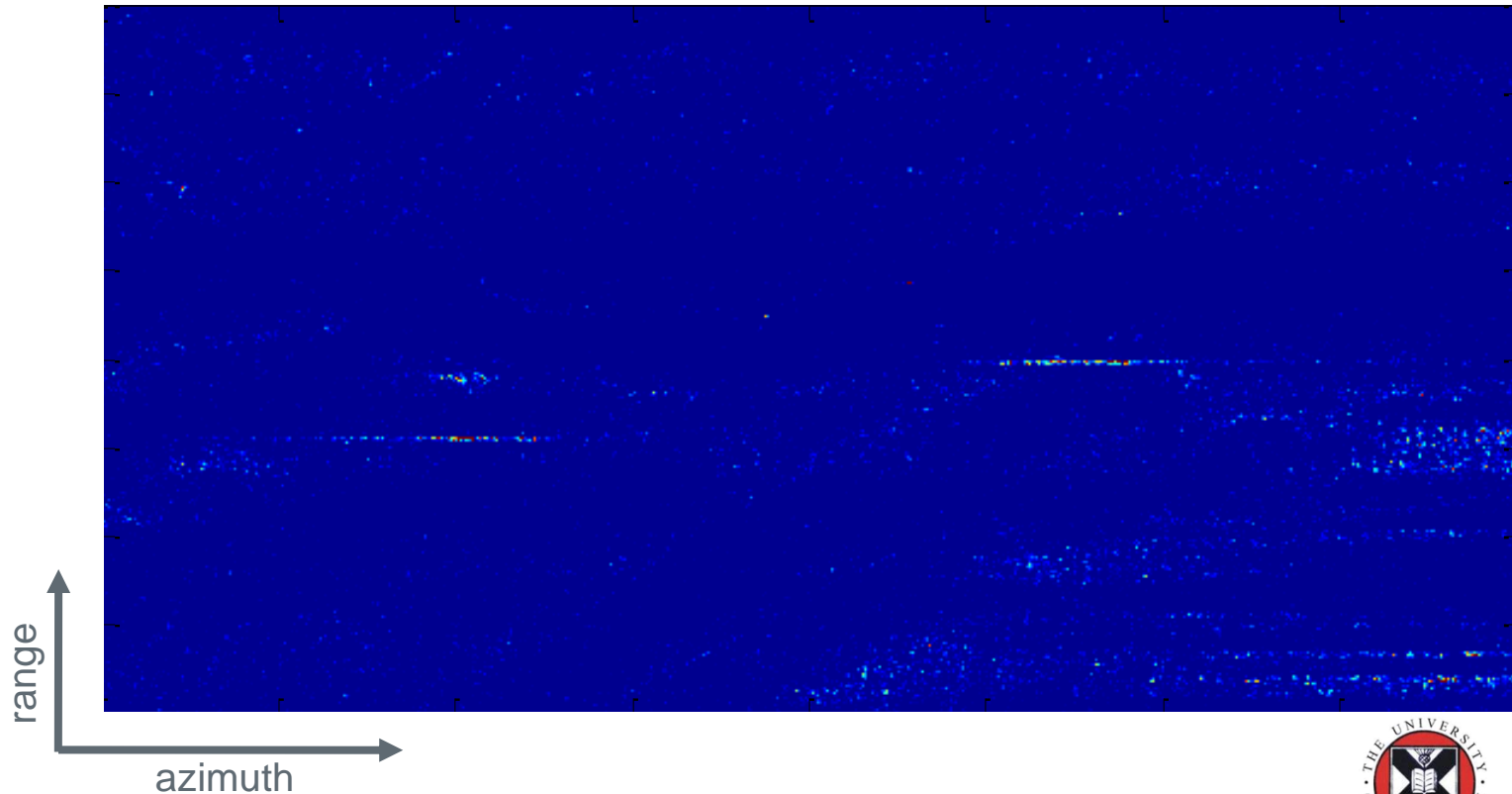
- ✦ DPCA and ATI have opposing strengths and weaknesses: so combine them.
- ✦ Resulting smears are very distinct over background
- ✦ Detection algorithms have proved to be successful



Post-Doppler STAP

Coastal trial after clutter removal

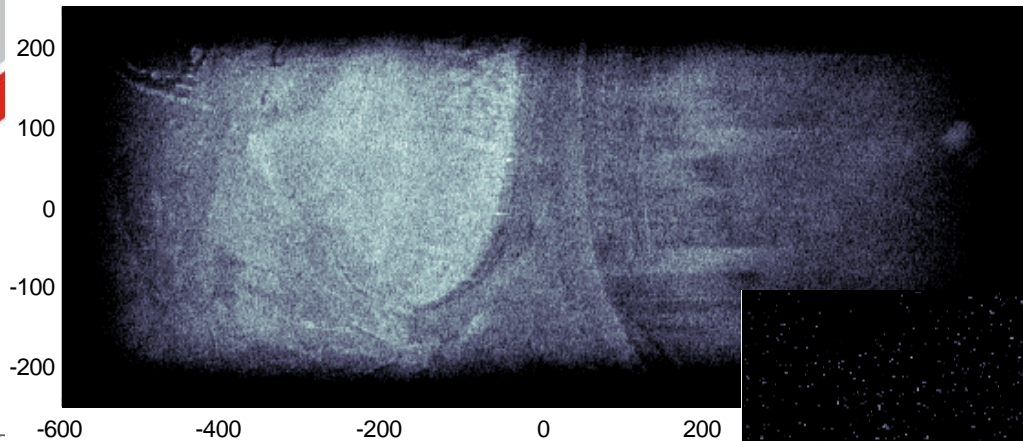
- ✦ Post-Doppler STAP offers slight improvement against hybrid DPCA/ATI
 - Far greater computational cost
 - More susceptible to clutter statistical variations
- ✦ Research aware of practical limitations within industry



Coastal helicopter trial

PD-STAP Clutter Suppression and Hybrid DPCA/ATI Comparison

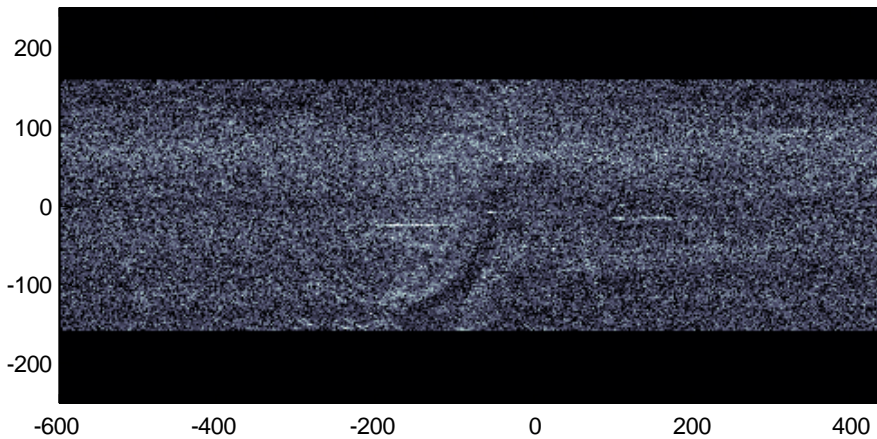
Original Image



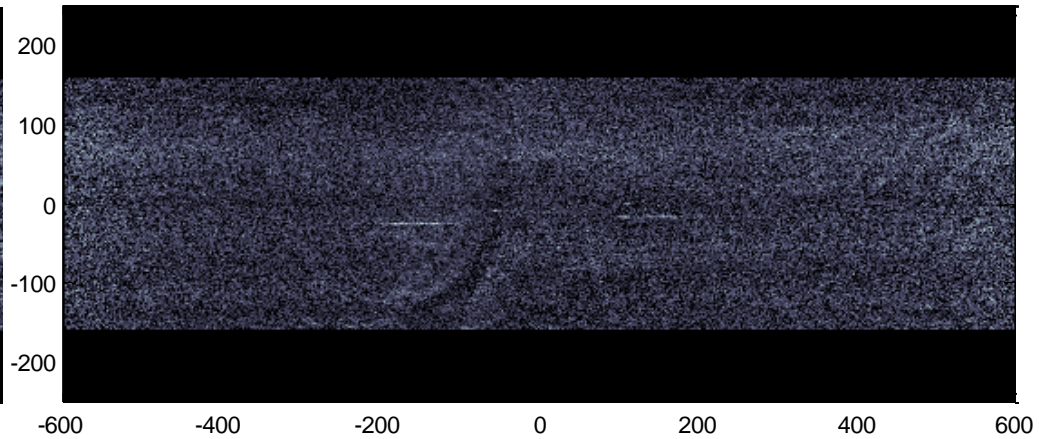
Hybrid DPCA/ATI



STAP Suppression

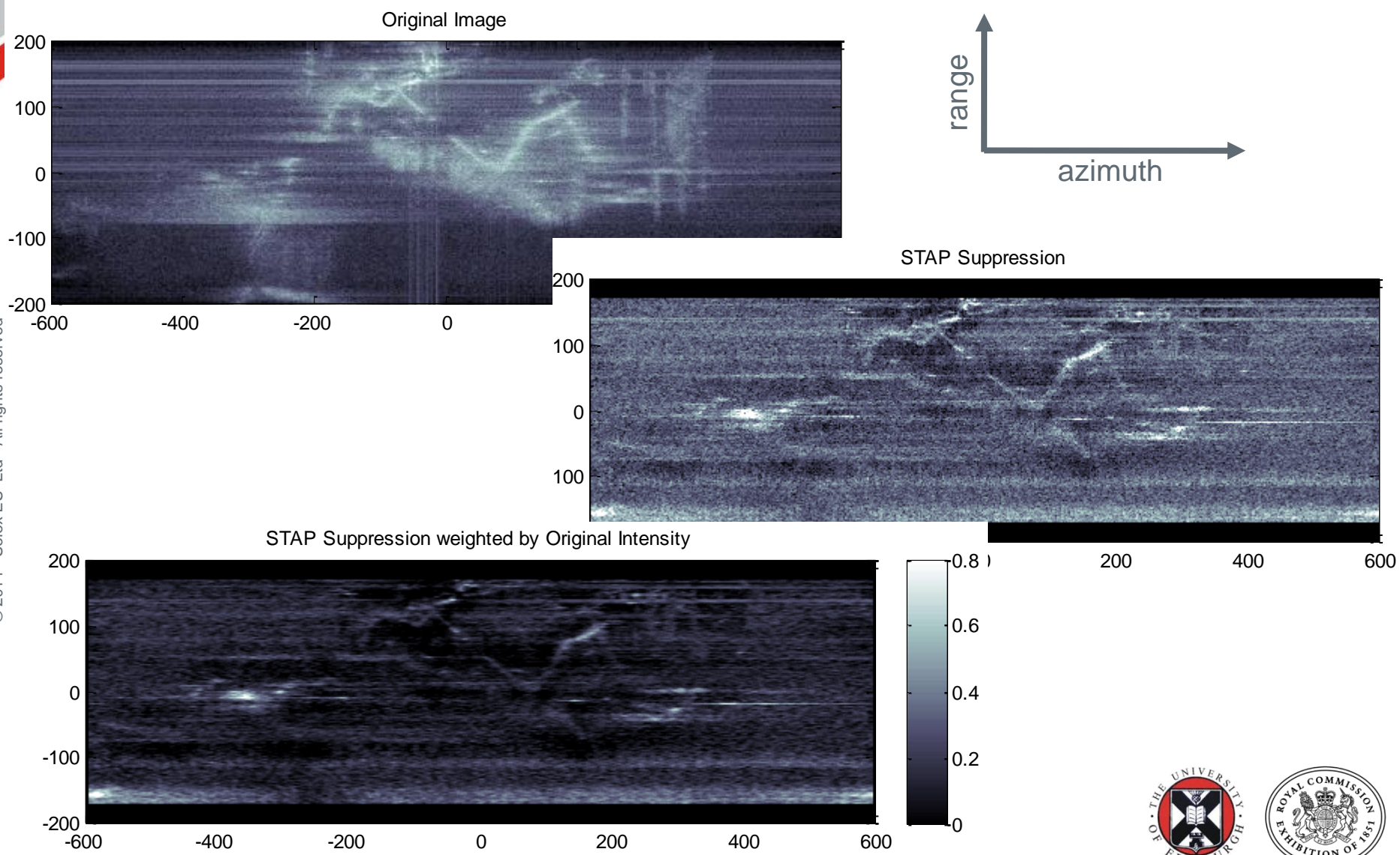


STAP Suppression weighted by Original Intensity



PicoSAR in a Van

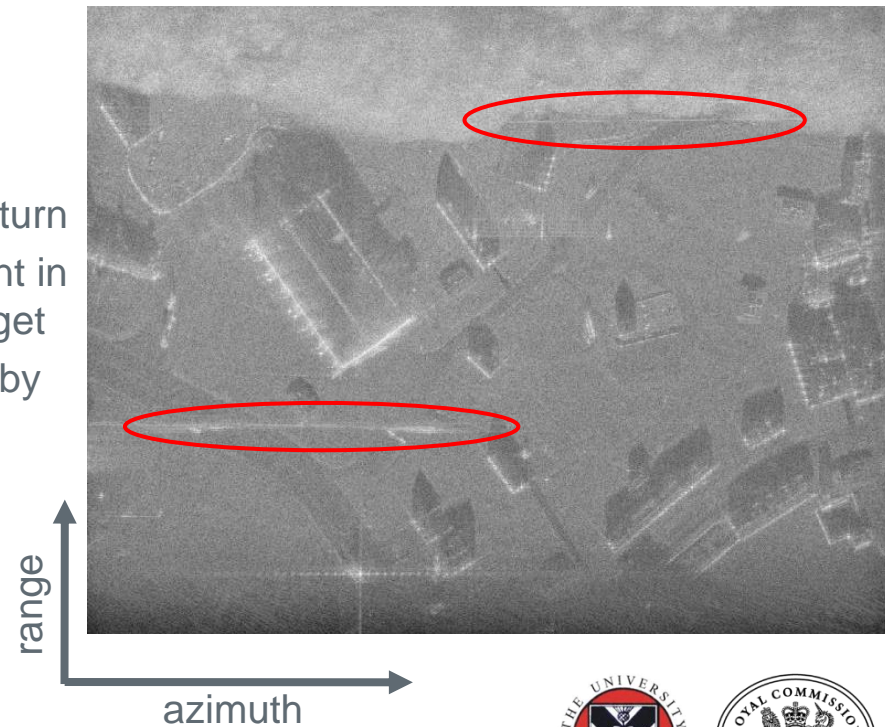
PD-STAP Clutter Removal on Farm Trial



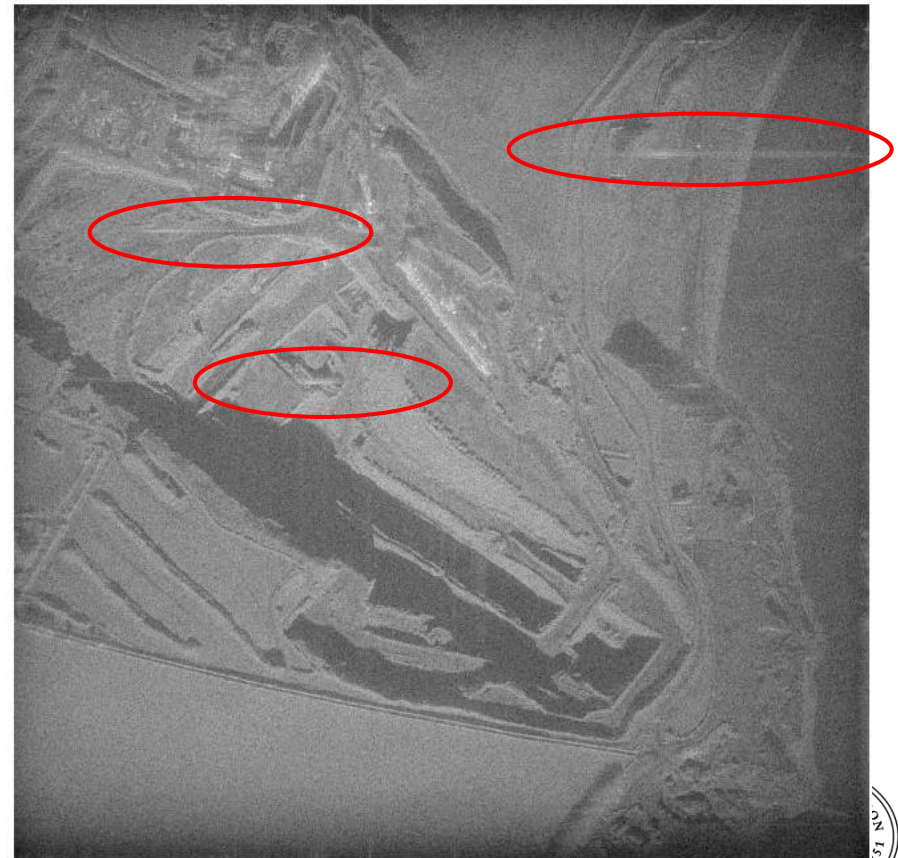
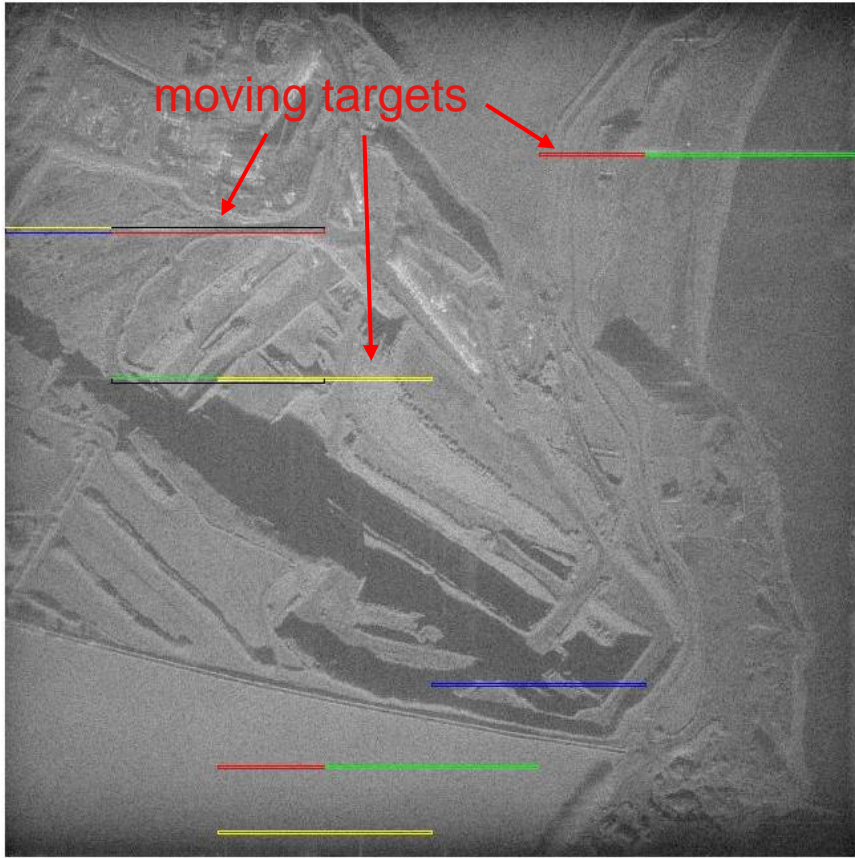
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- ✦ Utilises autofocus which is currently used in PicoSAR
 - Applies the same correction to the entire image; correcting errors that are constant across the entire scene from unknown platform motion
 - Autofocus does not focus anomalous phase errors arising from moving targets
- ✦ This SAR-MTI method is post-processing
 - Easier to add to existing systems
- ✦ Splits the image into patches
 - Patches are narrow in range, long in azimuth to match expected smear
- ✦ Autofocus is then applied to each patch in turn
- ✦ Those patches which show an improvement in sharpness after PGA contain a moving target
 - Static patches will have been focused by the global PGA and will show limited improvement

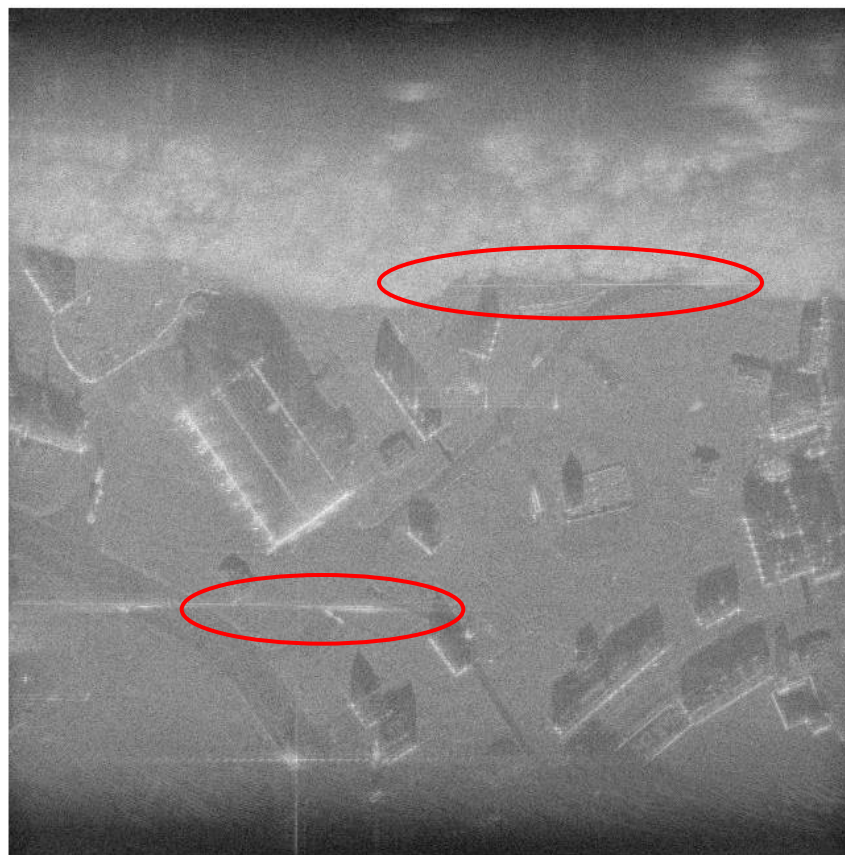
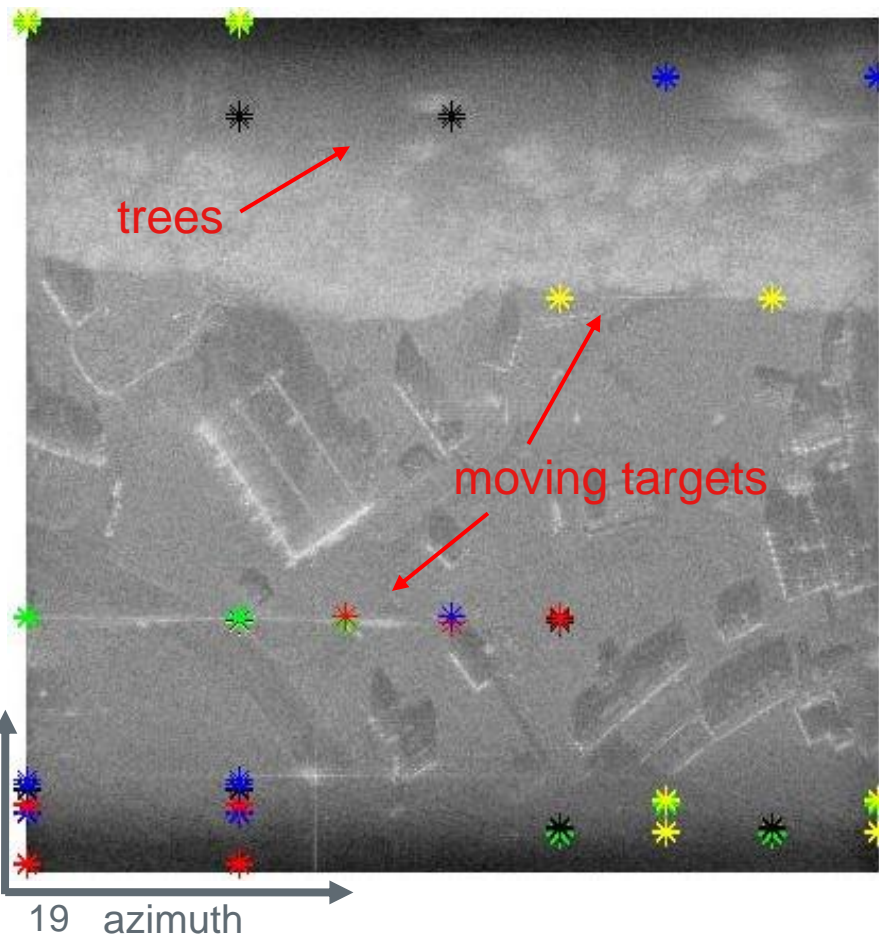


- ☀ Good detection
 - Patches with moving targets identified in coloured boxes in left image
- ☀ Very large, bright moving targets



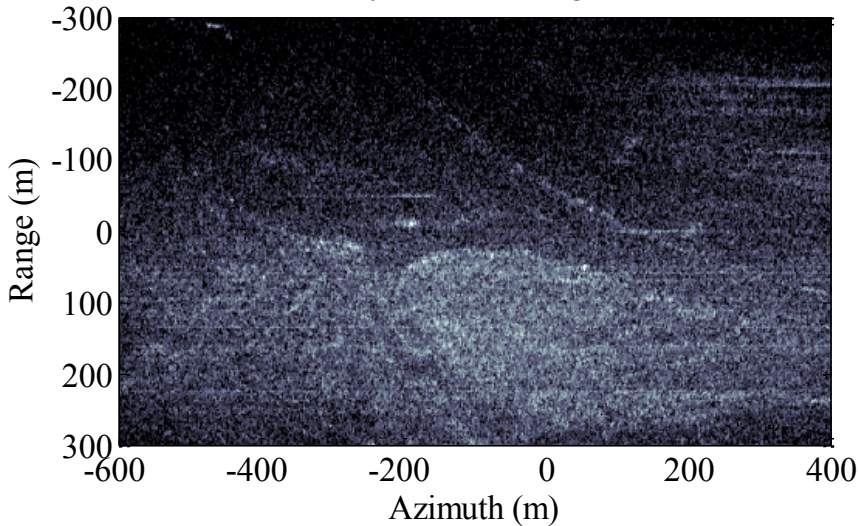
range ↑
18 azimuth →

☼ Targets seemingly identified but high number of suspected false alarms

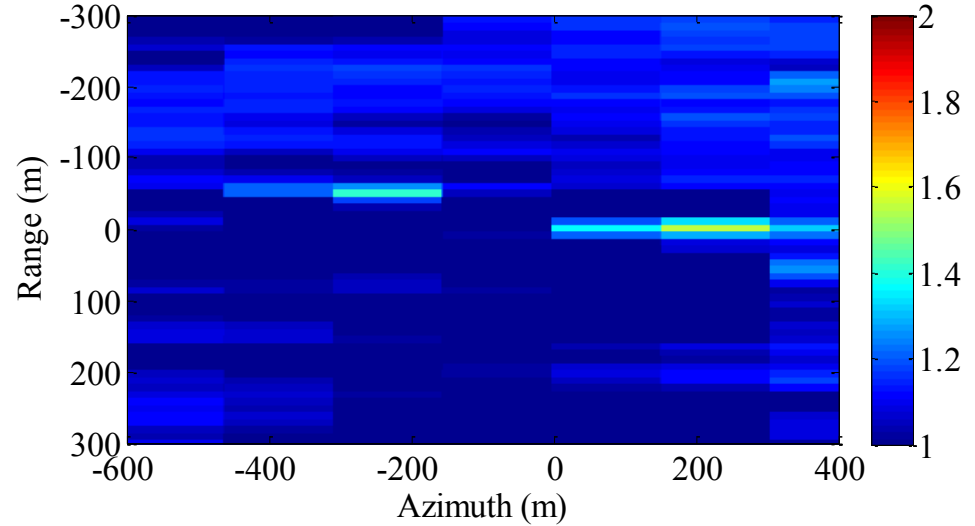


- ✦ Many false alarms due to crude thresholding of sharpness improvement
 - Phase error not always from moving objects of interest, eg. foliage (exclude clusters of patches?)
- ✦ Moving targets have to be in image to be detected
 - Will not detect fast moving targets outwith background Doppler-spread
 - Will not detect targets buried under strong clutter
- ✦ Excellent detector after clutter suppression

Hybrid MTI Image



Patch sharpness improvement



- ✦ Engineering Doctorate
 - Bernie Mulgrew at The University of Edinburgh
 - David Greig at Selex ES

- ✦ Industrial involvement in academia
- ✦ Academic involvement in industry

- ✦ Detecting moving targets in SAR images by enhancing traditional techniques
 - DPCA
 - ATI
 - Hybrid combination
 - STAP
 - MTI by patch-specific focusing

- ✦ Research facilitated throughout with Selex ES data





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