

Timing is everything: model-based and learning-based reconstruction methods for event-driven cameras

Pier Luigi Dragotti

Motivation

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Motivation (cont'd)

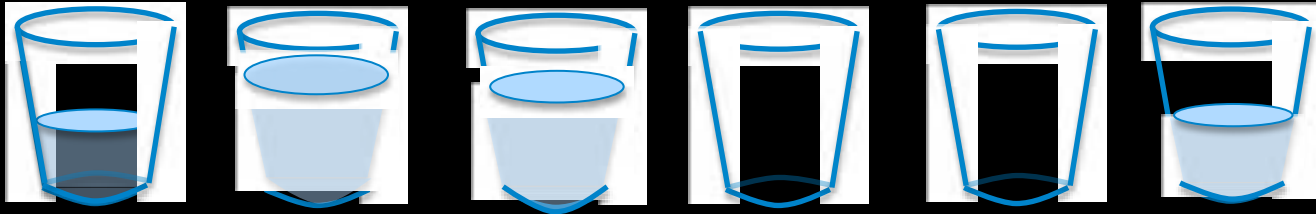
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Outline

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Bio-Inspired Energy Efficient Sensing

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Bio-Inspired Energy Efficient Sensing

Approach 2

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Bio-Inspired Energy Efficient Sensing

Approach 2
and-fire neurons

integrate-

Time encoding appears in nature

efficiently

very



Time-Encoding Machines

Integrate-and-fire System



Reconstruction from time-encoded information

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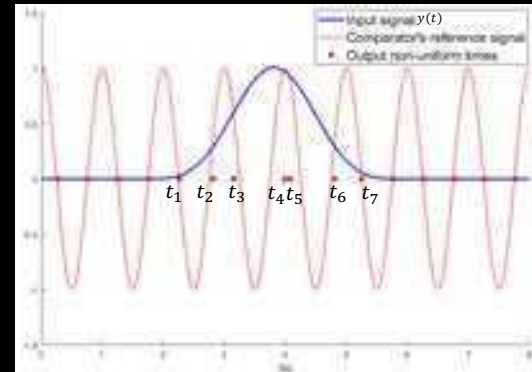
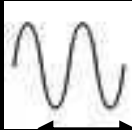
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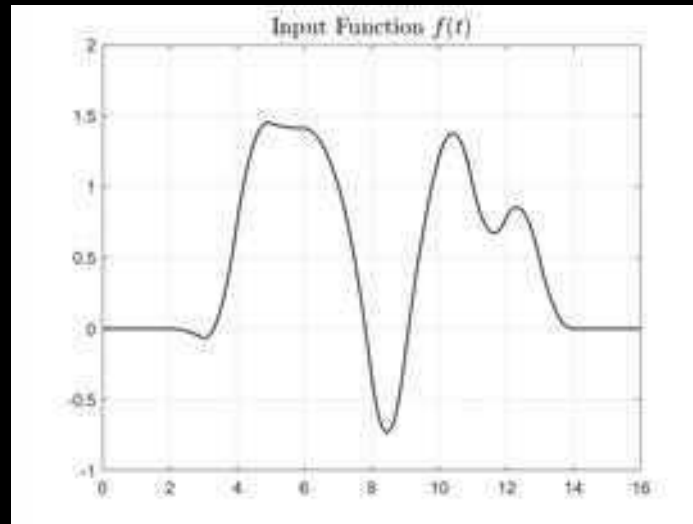
Time-Encoding Machines

Comparator System



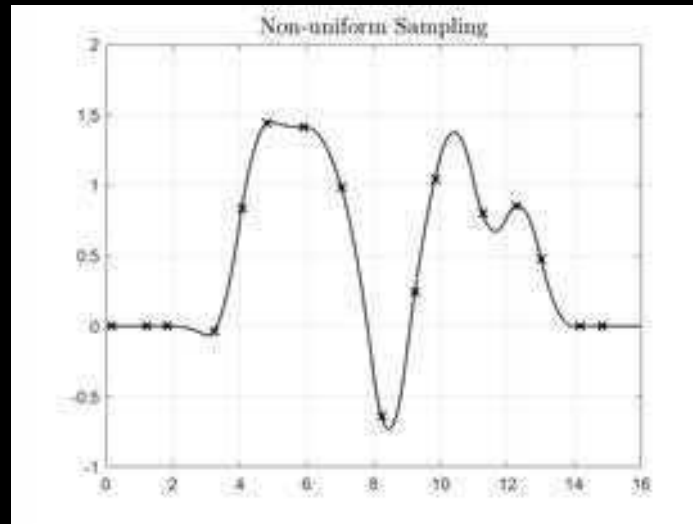
Reconstruction from time-encoded information

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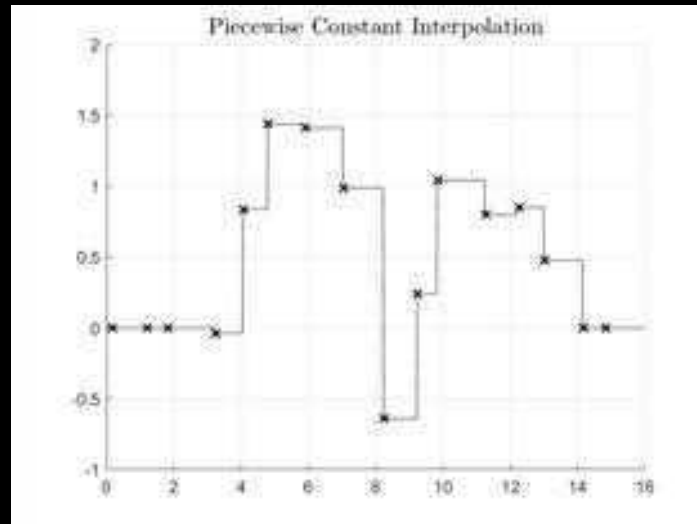
Reconstruction from time-encoded information

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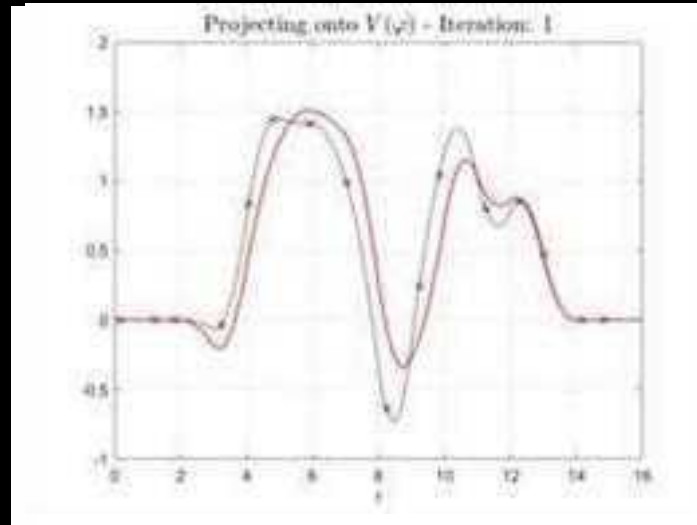
Reconstruction from time-encoded information

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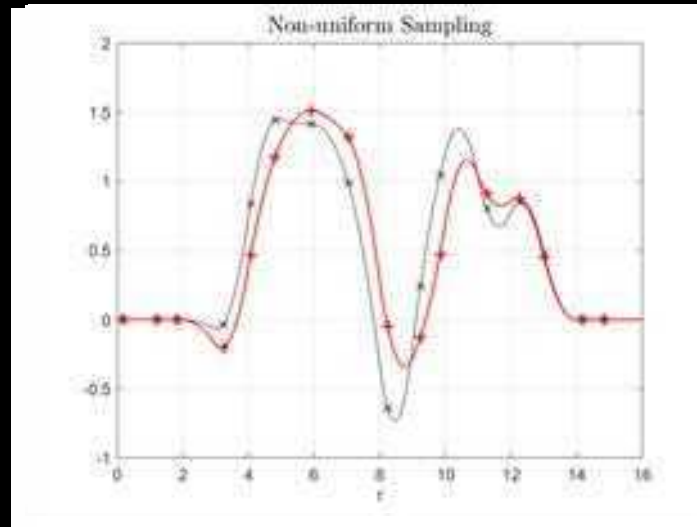
Reconstruction from time-encoded information

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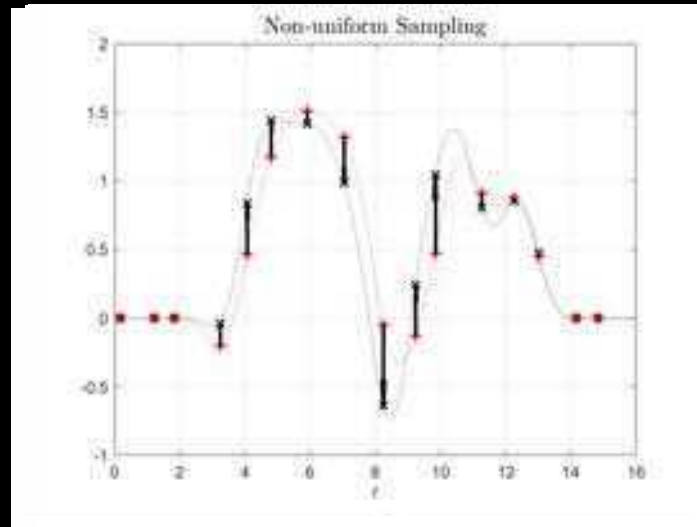
Reconstruction from time-encoded information

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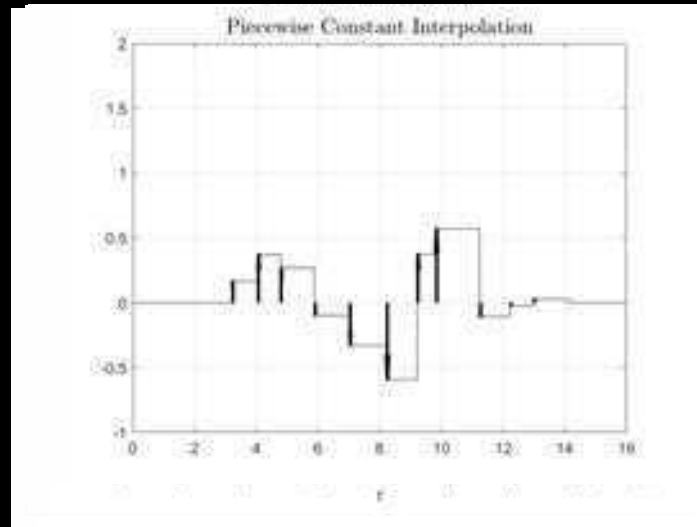
Reconstruction from time-encoded information

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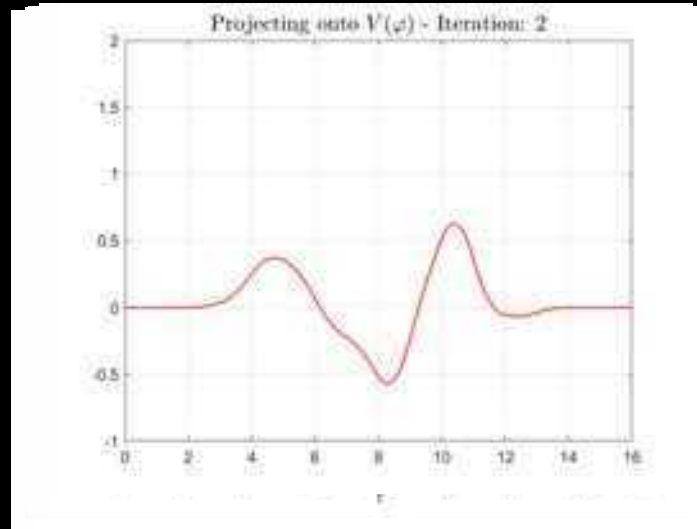
Reconstruction from time-encoded information

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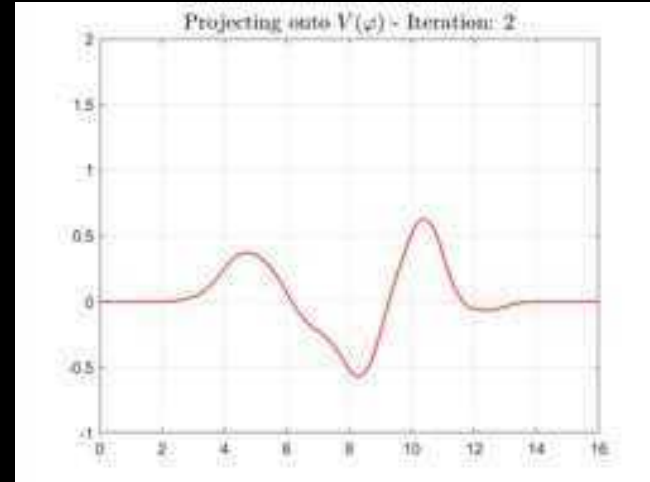
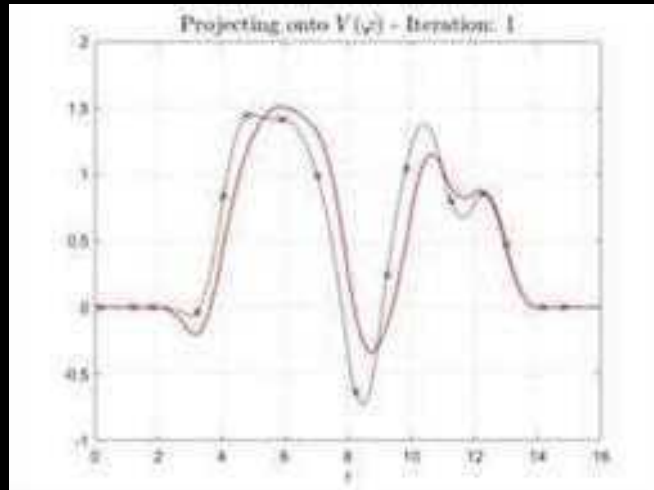
Reconstruction from time-encoded information

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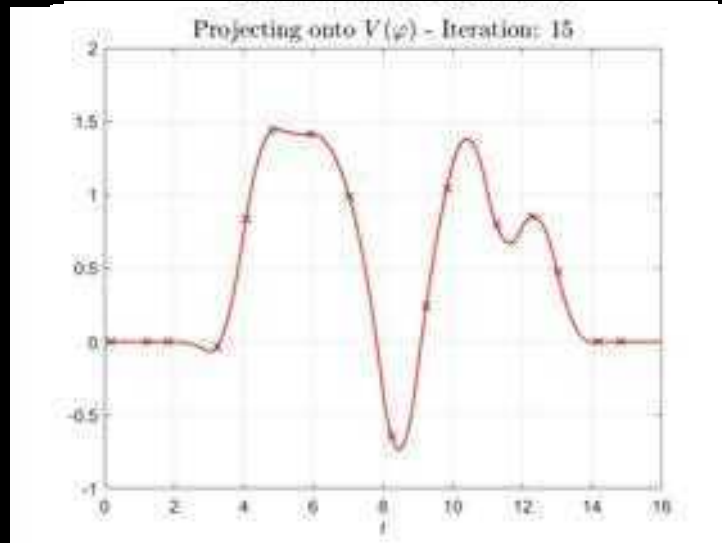
Reconstruction from time-encoded information

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Reconstruction from time-encoded information

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Reconstruction from time-encoded information

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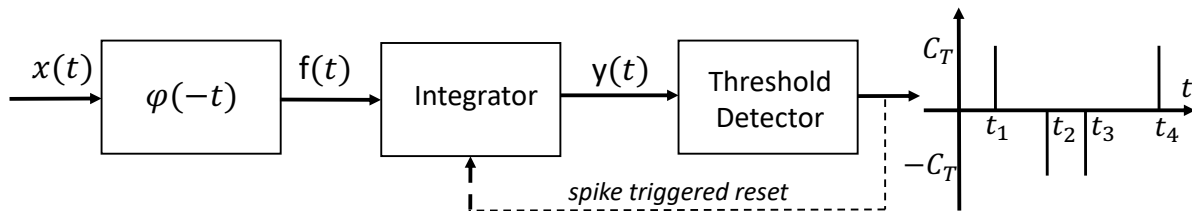
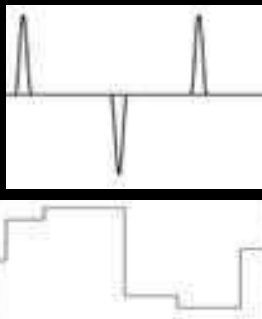
Time-based Sampling of Sparse Signals

Signals:

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Sensing Systems:

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Our approach for time decoding of signals

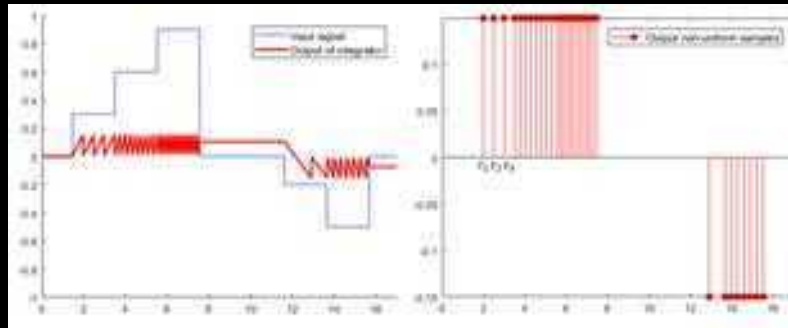
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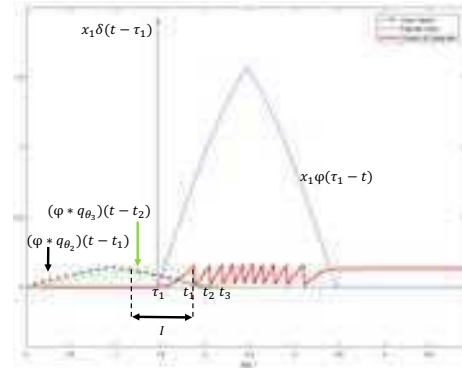
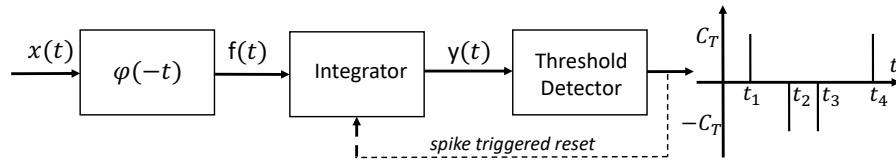
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Integrate and Fire TEM

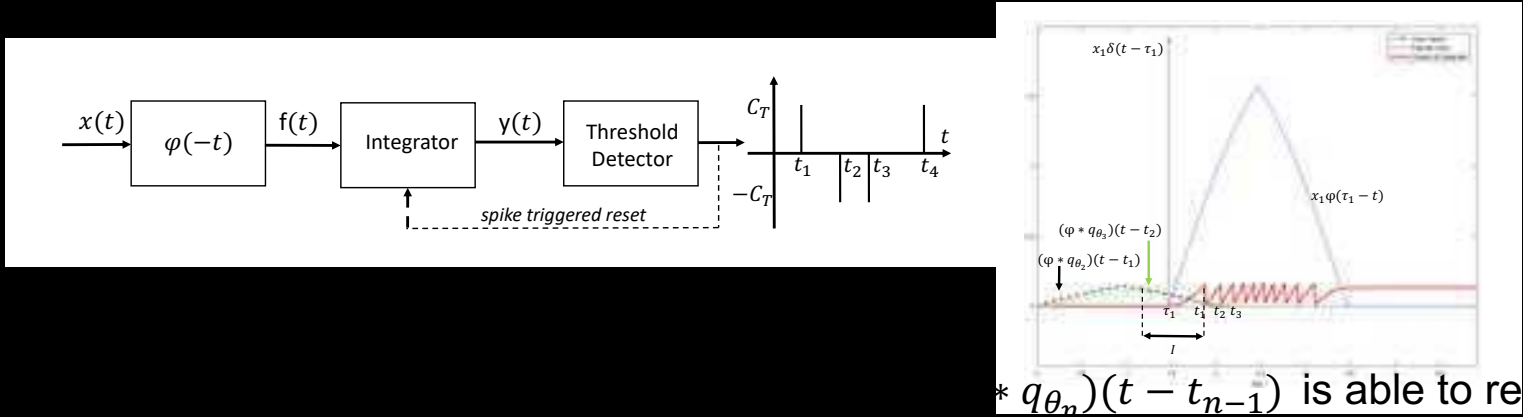


$$y(t_n) = \langle x(t), (\varphi * q_{\theta_n})(t - t_{n-1}) \rangle,$$

where $\theta_n = t_n - t_{n-1}$ and $q_{\theta_n}(t)$ is defined as:

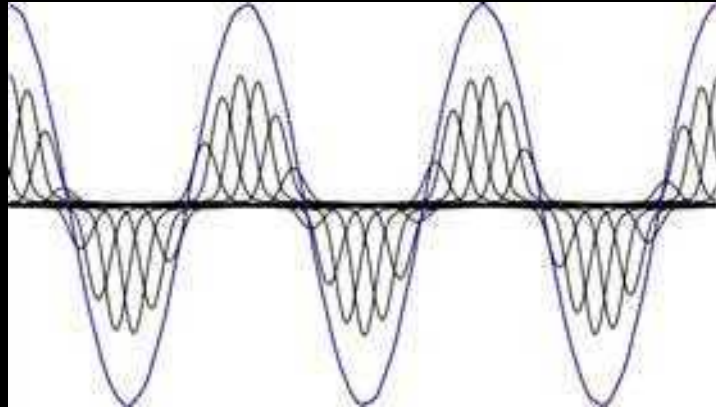
$$q_{\theta_n}(t) = \begin{cases} 1, & 0 \leq t \leq \theta_n, \\ 0, & \text{otherwise.} \end{cases}$$

Integrate and Fire TEM



- *Proposition:*

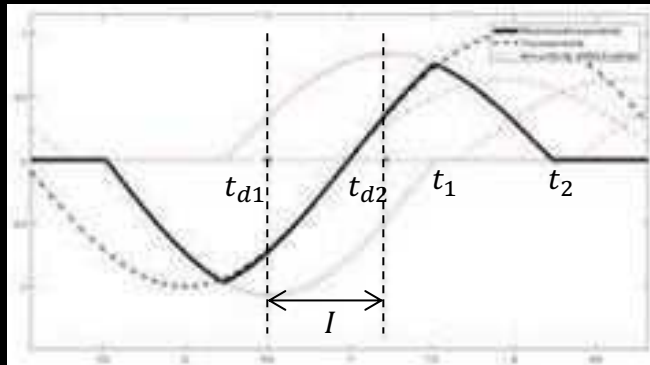
Reproduction of Exponentials



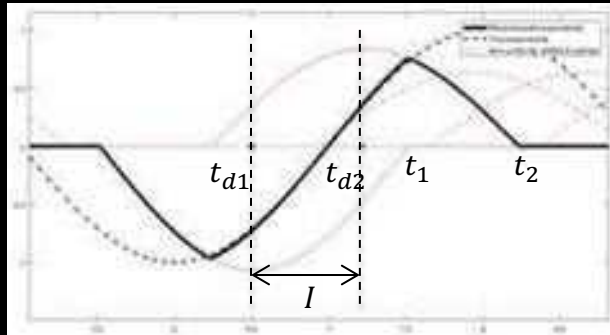
Reproduction of Exponentials

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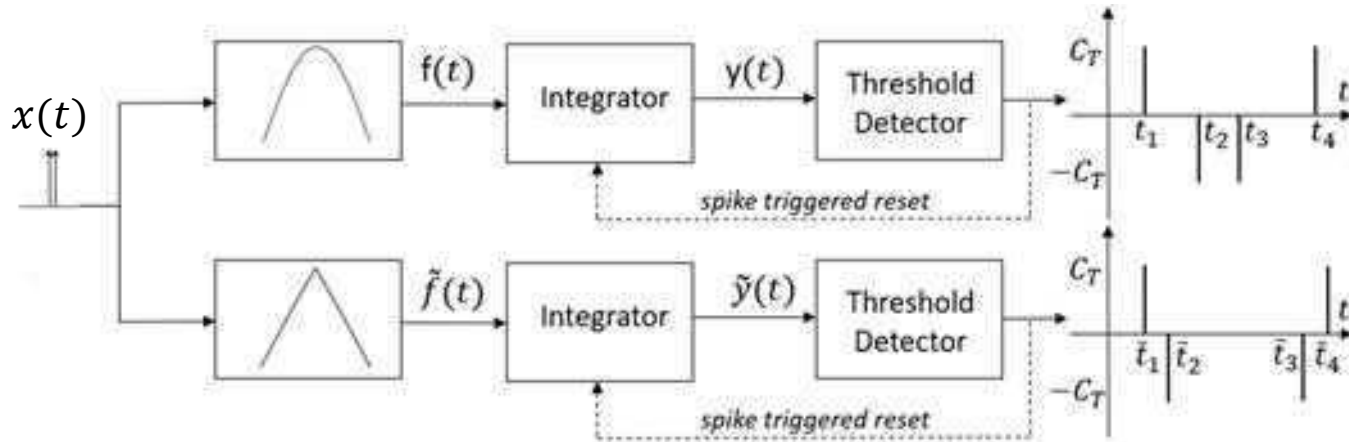
Reconstruction of an input Dirac from time-encoded information



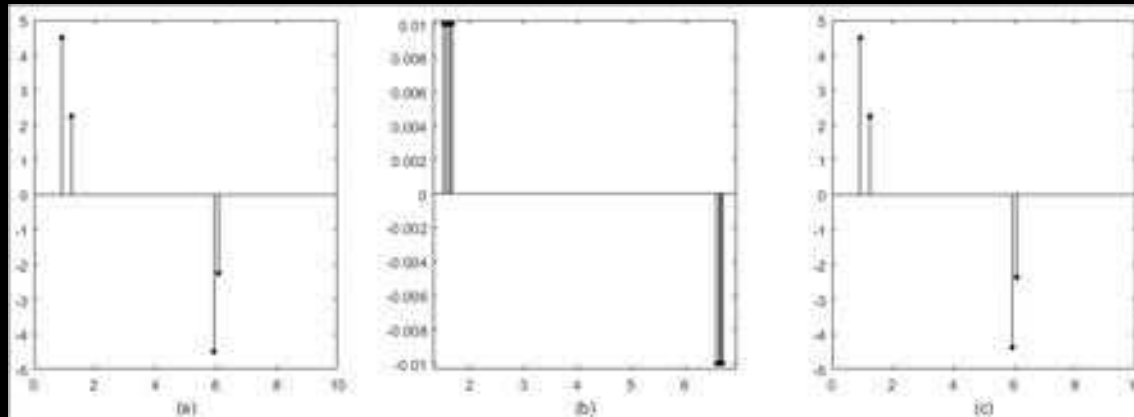
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$$\begin{array}{cccc}
 & & x_1 & \tau_1 \\
 & c_1 & c_2 & d_1 & d_2 \\
 c_1 & & c_2 & & \\
 d_1 & & d_2 & & \\
 \\
 c_1 & c_2 & x_1 & c_1 & \tau_1 & c_2 & \tau_1 & x_1 & \tau_1 \\
 d_1 & d_2 & x_1 & d_1 & \tau_1 & d_2 & \tau_1 & x_1 & \tau_1
 \end{array}$$

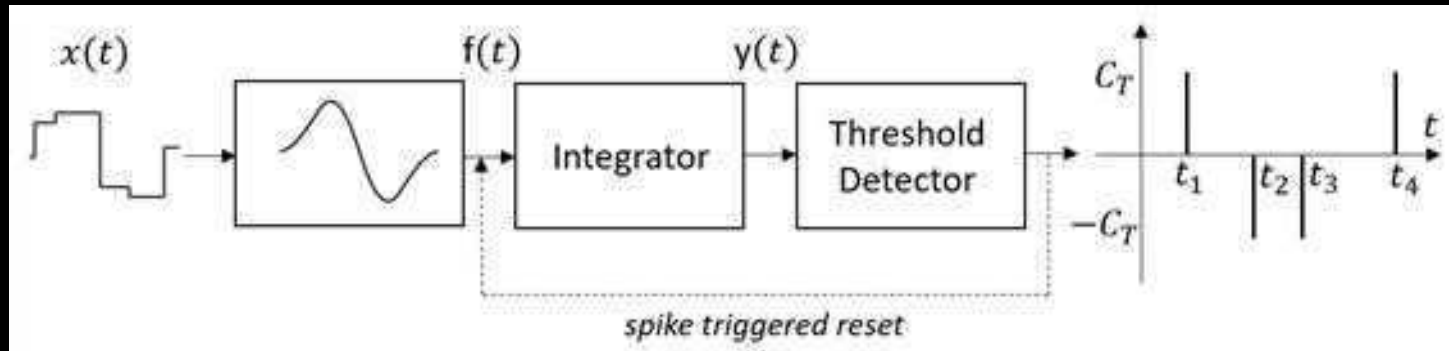
Reconstruction of close pulses



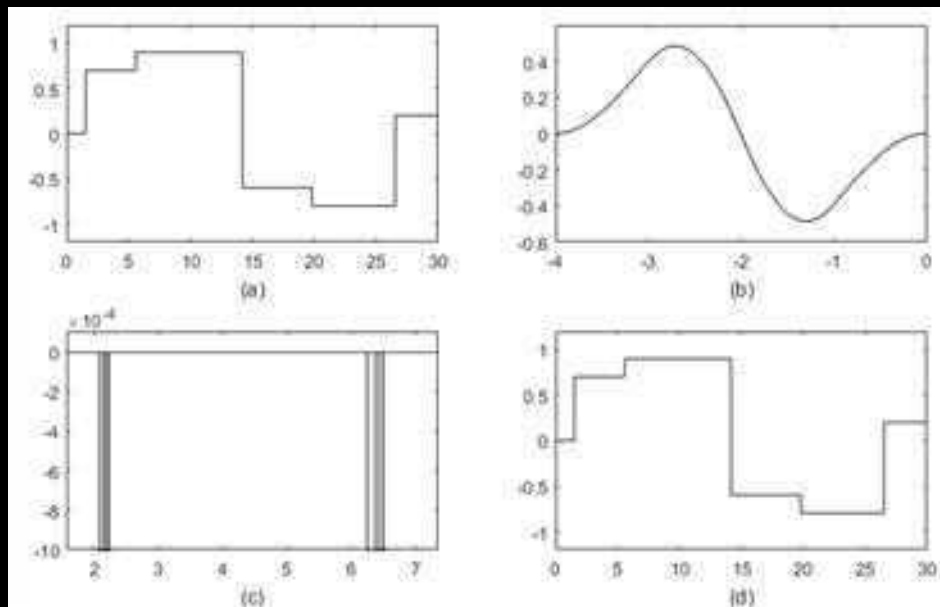
Integrate and Fire – Reconstruction of Pulses



Integrate and Fire – Piecewise Constant Signals



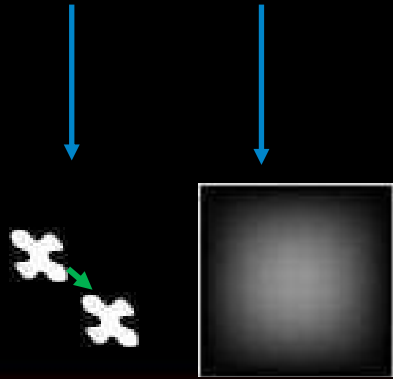
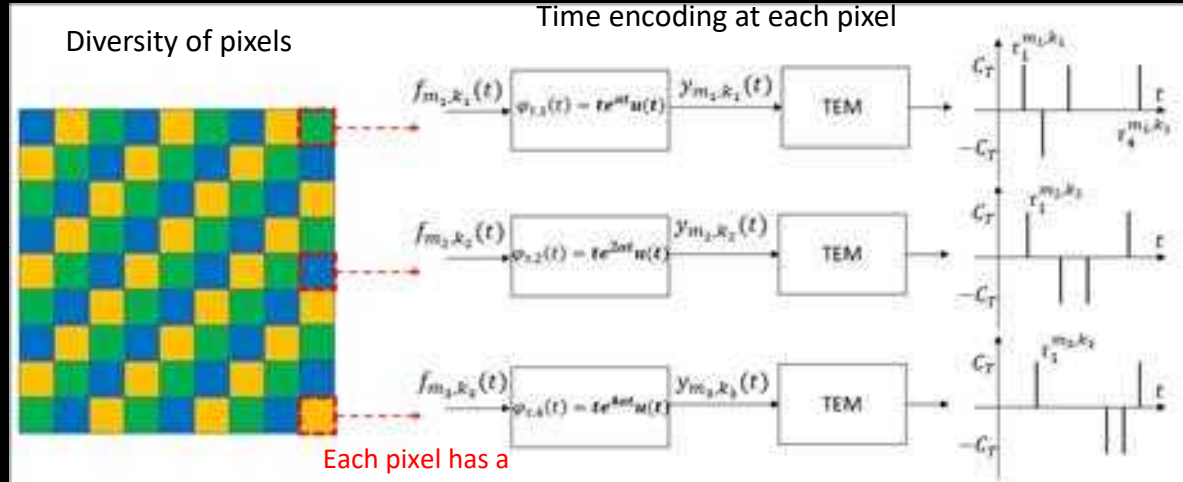
Energy Efficient Sampling -Results



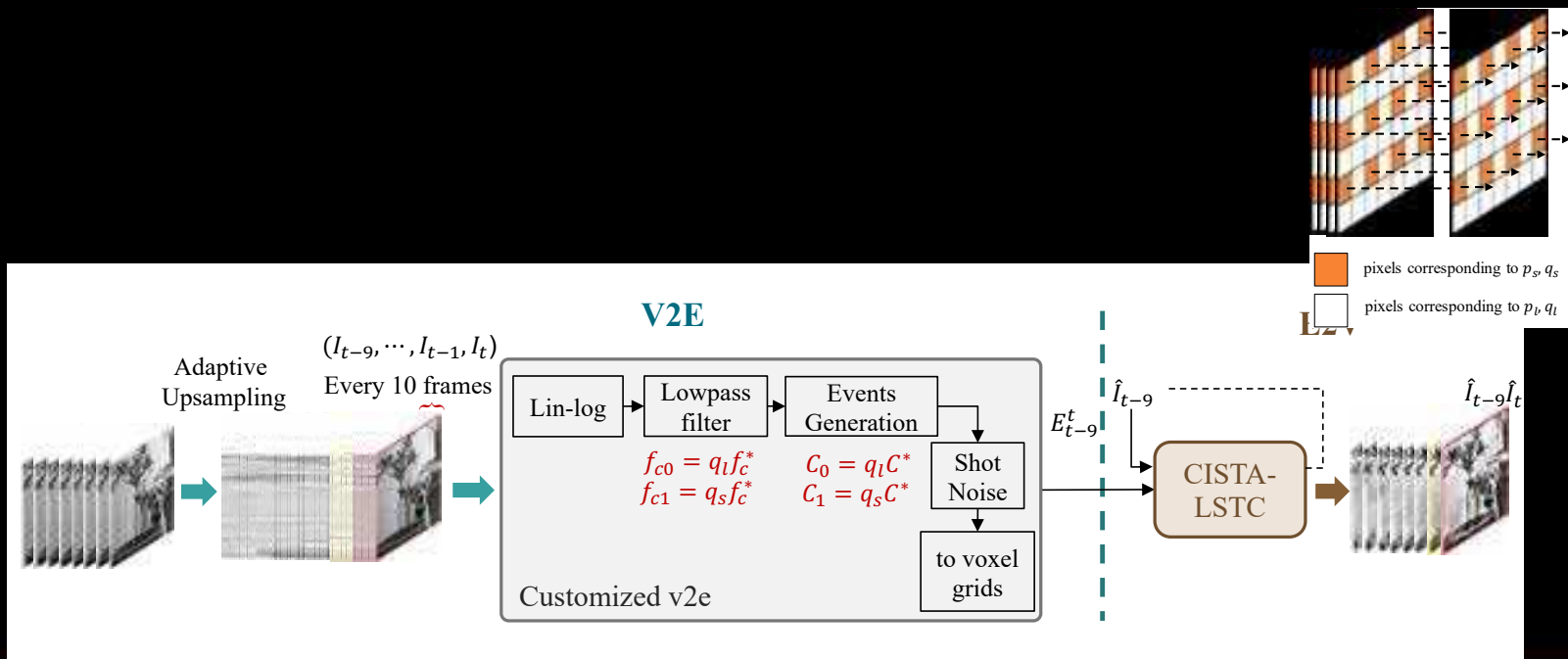
more efficient



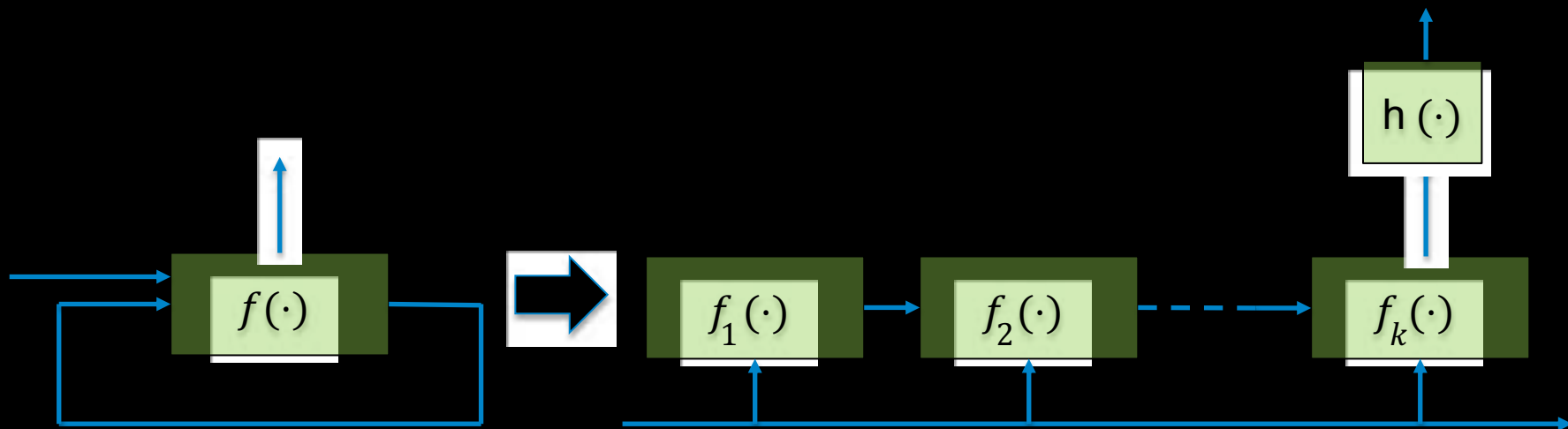
Integrate and Fire and Neuromorphic Cameras



Sensing Diversity for Neuromorphic Cameras

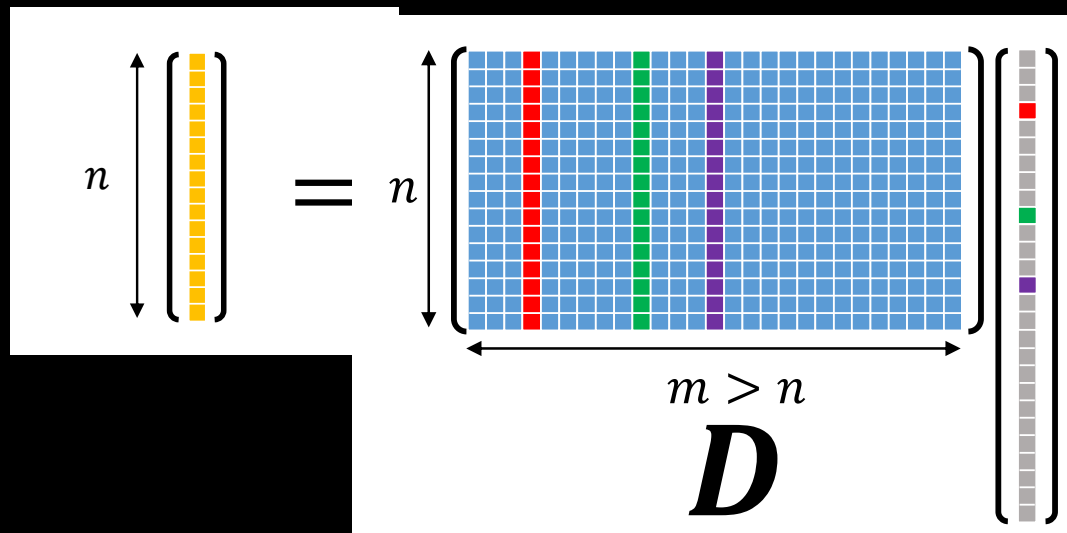


Deep Unfolding Strategy

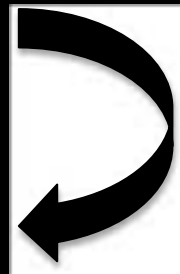
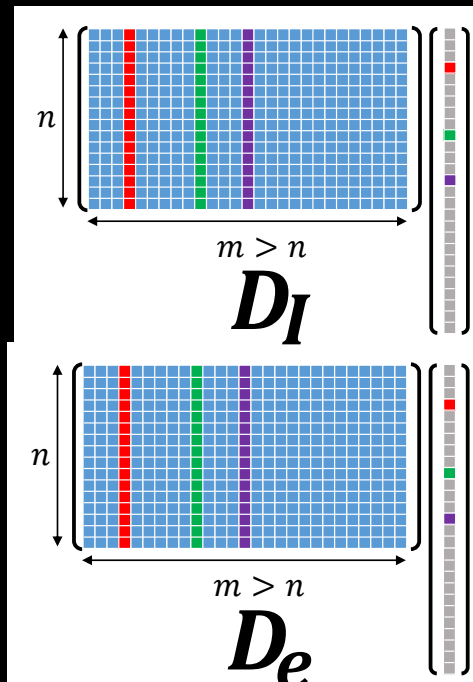


Dictionary Learning

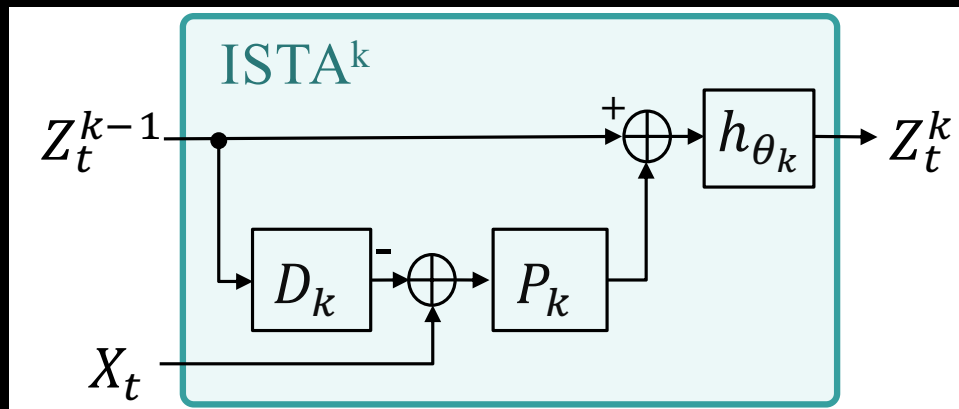
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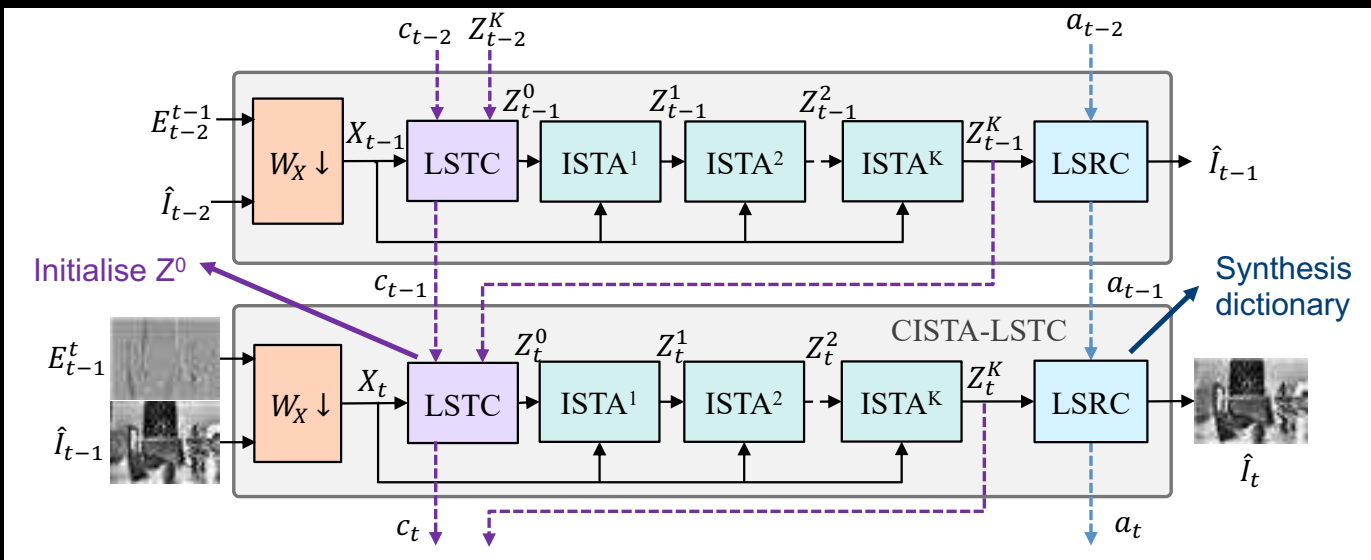
Model of dependency between intensity and events



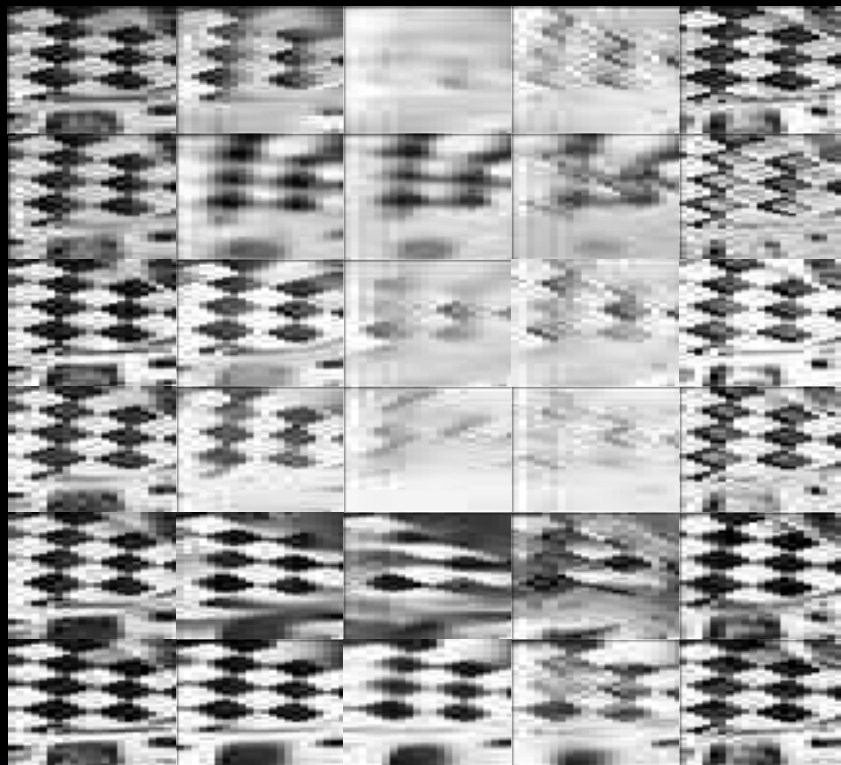
Deep Unfolding Strategy



Model-based reconstruction from events



Model-based reconstruction from events



Conclusions



Thank you!

References

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