

UDRC Summer School Programme – 26th June to 29th June 2017, Surrey University

	Statistical Signal Processing Monday 26 th June*	Radar Processing and Tracking Tuesday 27 th June	Machine Learning Wednesday 28 th June**	Source Separation and Beamforming Thursday 29 th June
08:30	Coffee	Coffee	Coffee	Coffee
09:00	Introduction and Target Localisation: Discussion of target localisation as exemplar application for the day's material. Probability and Random Variables: Probability and classic paradoxes; random variables; probability transformations; statistical descriptors; central limit theorem; Monte Carlo methods; generating random variables. Classical Estimation Theory: Basic concepts; properties of estimators; Cramér–Rao lower bounds; maximum likelihood; Bayes theorem; least squares. The theory will be linked to a “breakdown” of the localization problem. <i>James Hopgood, University of Edinburgh</i>	Introduction to Radar Signal Processing: Basic Radar principles; data collection; Doppler processing, matched filter, pulse compression, ambiguity function (AF), coherent processing, demos. <i>Christos Ilioudis, Strathclyde University</i>	Introduction to machine learning: Basic concepts; problem formulation: data, labels, objective function, constraints, regularization; examples in pattern classification; kernel PCA and KDA, Support Vector Machines, neural networks (NN). <i>Josef Kittler, University of Surrey</i>	Introduction to source separation: Instantaneous and convolutive mixing models; block and sequential blind source separation algorithms; applications. <i>Jonathon Chambers, Newcastle University</i>
10:00		Space-time Adaptive Processing (STAP) - Using J.Ward's Tech. Report 1015 (1994) as a guide: Airborne Array Radar Signal Environment, Space-Time Processing Fundamentals, Airborne Radar Clutter Signal, STAP Performance Evaluation, MatLab Demos . <i>Ilias Konsoulas, Hellenic Air Force</i>	Deep neural networks I: Introduction; Simple Feed Forward Neural Network architecture; How to train Neural Network; Backpropagation theory; Introduction to Convolutional Neural Networks. <i>Muhammad Rana, University of Surrey</i>	Principal component analysis (PCA): Independent component analysis (ICA); independent vector analysis (IVA); algorithms and tutorial examples. <i>Mohsen Naqvi, Newcastle University</i>
11:00	Refreshments	Refreshments	Refreshments	Refreshments
11:30	Introduction to Detection Theory: Using the results from the first session, consider classic parameter detection. Introduction to Random Processes: Ensembles, statistical descriptors; input-output system relationships; system identification; introduction to spectral representations. <i>James Hopgood, University of Edinburgh</i>	The Kalman filter: An introduction to Bayesian filtering through the example of the Kalman filter. <i>Daniel Clark, Heriot-Watt University</i>	Deep neural networks II: Deep learning architectures; Key factors behind deep learning; Residual Neural Networks; Latest developments in neural Network architectures. Some applications as examples of deep learning. <i>Muhammad Rana, University of Surrey</i>	Convolutive source separation: Exploiting signal properties; nonstationarity and sparsity; and deep learning algorithms and tutorial examples. <i>Wenwu Wang, University of Surrey</i>
13:00	Lunch	Lunch	Lunch	Lunch
14:00	Optimal and Adaptive Filtering of stochastic processes: Spectral representations of stochastic processes; Optimal Wiener filtering; Adaptive processing for optimal filtering in practice; LMS and RLS algorithms, application examples. Optimal detection of signals: Application examples, Optimal tests in the white and colored noise cases. <i>Murat Uney, University of Edinburgh</i>	Sequential Monte Carlo Methods: Particle filtering and extensions for engineering applications. <i>Flávio Eler de Melo, Heriot-Watt University</i>	Deep neural networks III: Recurrent Neural Networks (RNN), Long Short-Term Memory (LSTM), and their applications in computer vision and natural language processing. Practical issues in using popular deep learning libraries including Caffe, Torch, TensorFlow, Matconvnet. <i>Fei Yan, University of Surrey</i>	Polynomial matrices and decompositions: Tutorial examples. <i>Stephan Weiss, University of Strathclyde</i>
15:30	Refreshments	Refreshments	Refreshments	Refreshments
16:00 – 17:00	Examples, Applications, and Closing Remarks: Worked examples and application areas of presented theory. Summary of topics for further study, e.g.: state-space models, Kalman filter; Chapman-Kolmogorov equation. Summary and conclusions of key points from the day. <i>Murat Uney and James Hopgood, University of Edinburgh</i>	Beyond the PHD filter: Multi-target tracking for scenarios with a high variance in the number of detections. <i>Isabel Schlangen, Heriot-Watt University</i>	Machine learning in anomaly detection Concept of anomaly; Anomaly as an outlier of a statistical distribution. Anomaly detection. Anomaly detection in graphs. Application to anomaly in communication networks. <i>Radek Marik, Czech Technical University Prague</i>	Beamforming and source localization: Tutorial examples on beamforming and source localisation <i>Stephan Weiss, University of Strathclyde</i>

*Monday 26th June 2017 at 5:30pm: Local drink and cheese tasting (outside the lecture theatre)

**Wednesday 28th June 2017 at 7.30pm: Summer school dinner at the Thai Terrace, Guildford

Links:

[Space-time Adaptive Processing \(STAP\) – MatLab code](#)