

# Exploiting Sparsity in Signal Acquisition, Separation and Processing

*Mike Davies*

UDRC Edinburgh Consortium

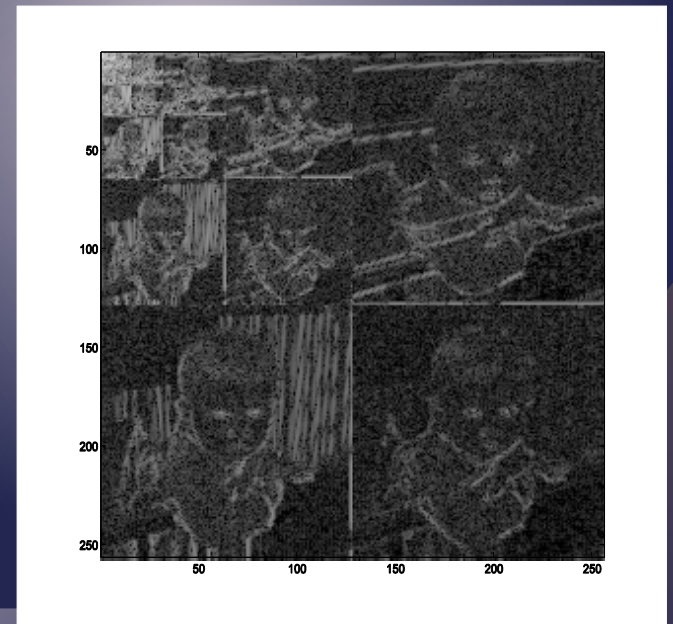
Joint work with

Shaun Kelly, Chaoron Du, Gabriel Rilling and Fabien Millioz

## Why Sparsity?



"TOM" image



Wavelet Domain

Sparsity indicates that the underlying dimension of data  $\ll N$

# Sparse Representations in Inverse Problems

# Sparsity & ill-posed Inverse problems

Linear Inverse Problems generally take the form:

$$Ax = y$$

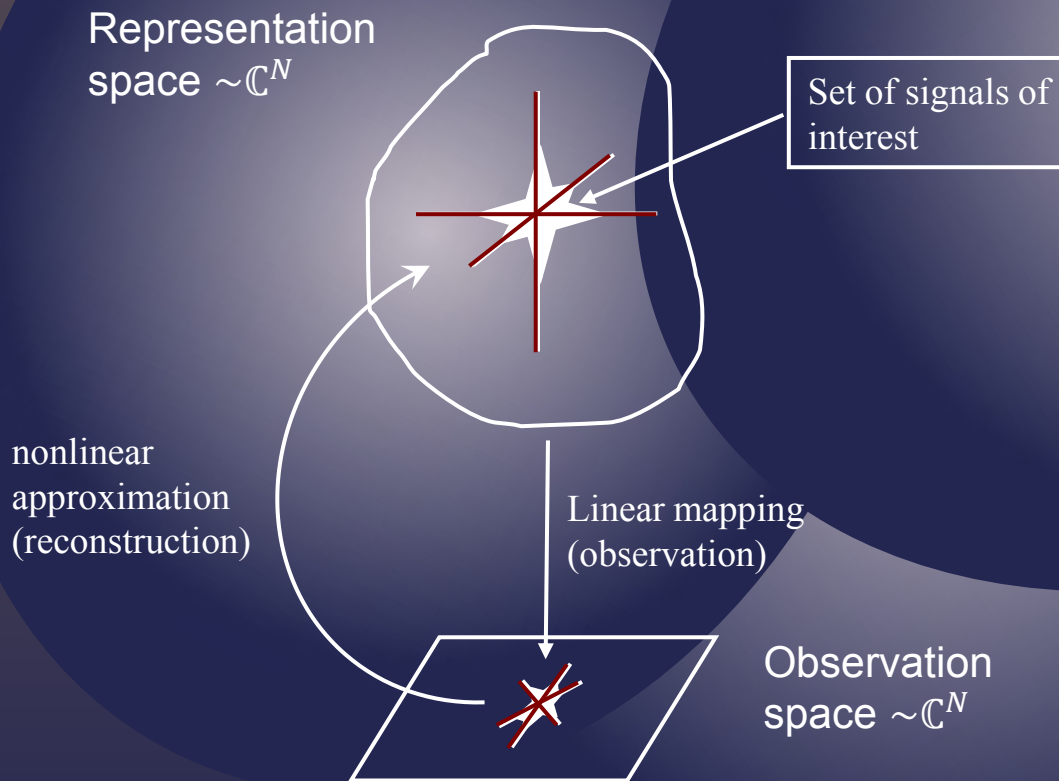
with  $x \in \mathbb{C}^N, y \in \mathbb{C}^m$ . If  $m < N$  then the problem is ill-posed. i.e. there are an infinity of solutions.

## Kruskal Rank

If  $x$  is  $K$ -sparse problem is still well posed if for all index sets  $|T| \leq 2K$  the submatrices  $A_T \in \mathbb{C}^{m \times 2K}$  are full rank...  $\text{krank}(A) \geq 2K$



# Recovering Sparse Representations



In order to recover a sparse representation the mapping must be invertible on the sparse set (an embedding)

For the solution to be stable we need a little bit more: restricted isometry property (RIP) ... a low distortion embedding

# Practical Reconstruction algorithms

Sparse recovery - combinatorial search:

$$x^* = \min_x \|x\|_0 \text{ such that } \|y - Ax\|_2 \leq \epsilon$$

But this problem is combinatorial and NP-hard. However there are practical solutions with guaranteed performance under RIP

Convex relaxation – solve  $l_1$  optimization e.g.

$$x^* = \min_x \|x\|_1 \text{ such that } \|y - Ax\|_2 \leq \epsilon$$

or greedy solutions – combine least squares minimization with hard subset selection, e.g. (orthogonal) Matching Pursuit, Iterative Hard Thresholding, etc.

# Sparsity & ill-posed Inverse problems

Sparse signal models help in a number of signal processing tasks such as...

Observation



Signal



Reconstruction



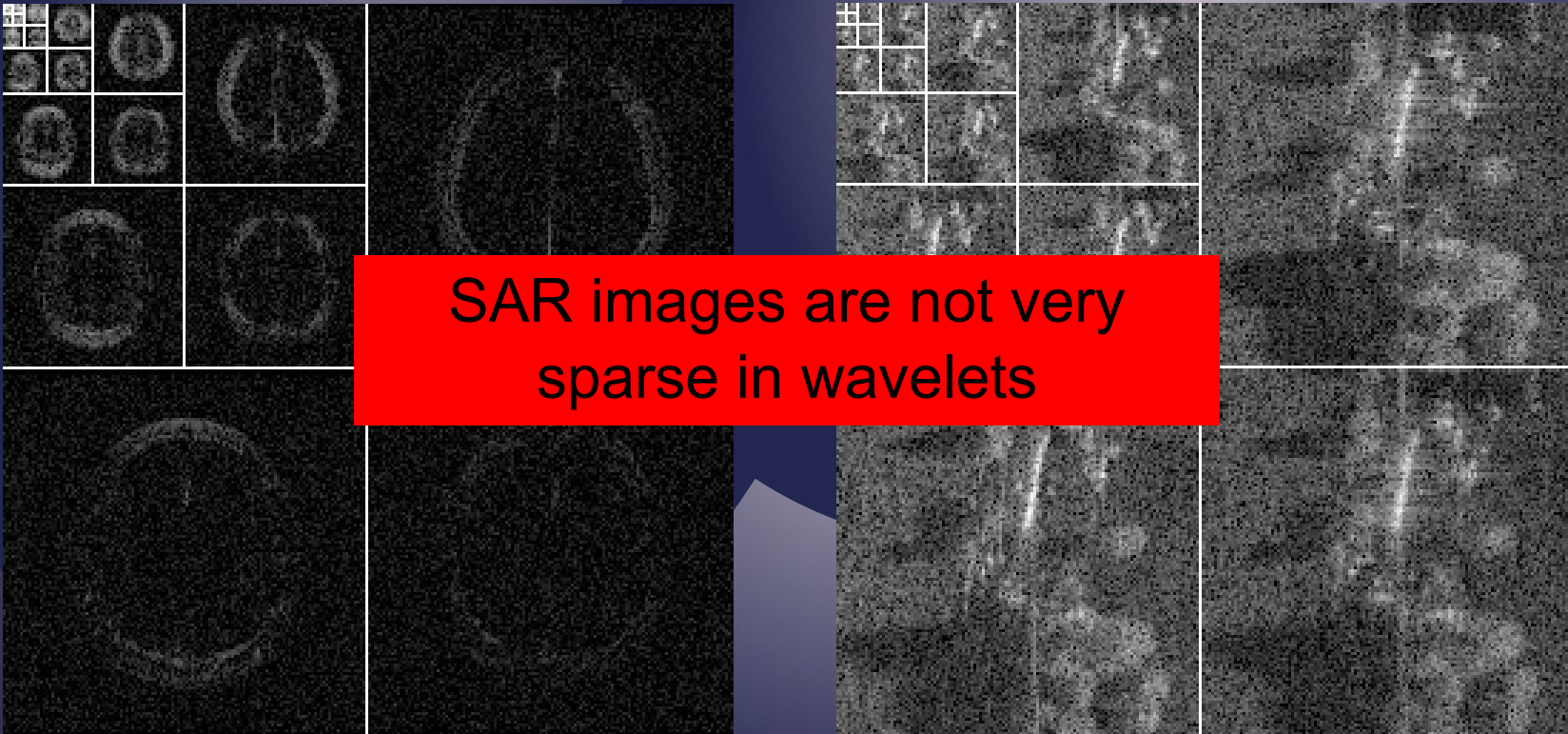
Missing Data Recovery  
Image De-blurring

# Sparsity in Synthetic Aperture Radar



## Sparsity model?

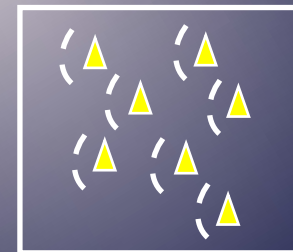
Unlike other Fourier based CS applications, e.g. MRI...



## SAR image statistics

SAR images composed of two main components:

1. Speckle dominated images due to multiple random reflectors in a single range cell - **not compressible**.
2. Coherent reflectors whose intensity can be  $\sim 10^3$  larger than incoherent reflections - **compressible in pixel domain**.



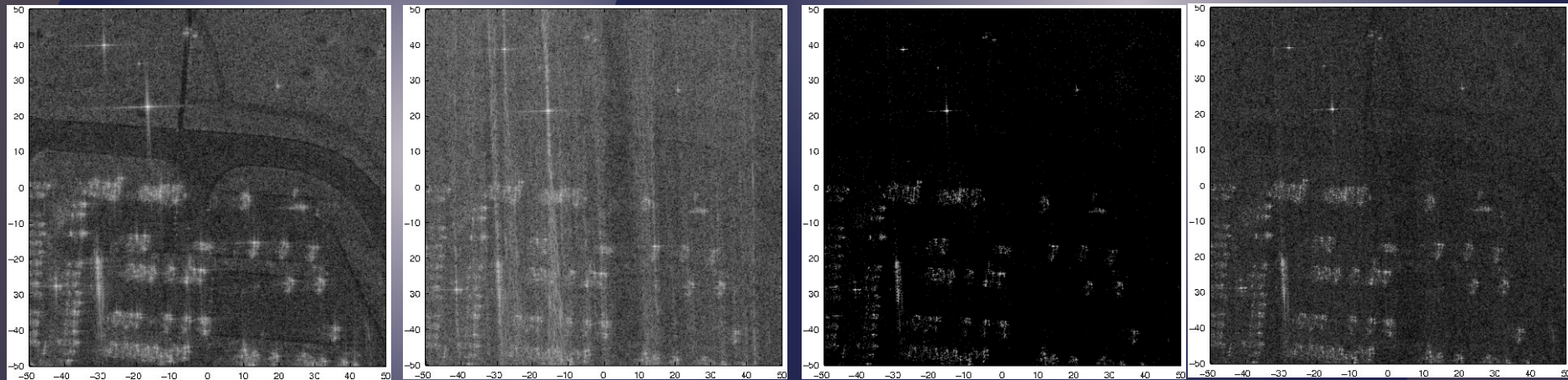
range cell



range cell

# CS SAR reconstruction from limited data

Compressed sensing can only extract the coherent points in the image:



fully sampled image

back projection

sparse CS

mixed  $l_1/l_2$

A mixed  $l_1/l_2$  solution

$$x^* = \min \|x\|_1 \text{ such that } \|y - Ax\|_2 \leq \lambda$$

$$\hat{x} = A^\dagger(y - Ax^*)$$

50% Nyquist



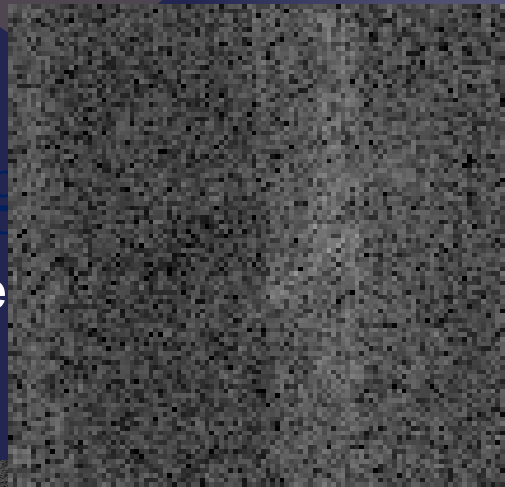
# Compressive target

Target's coherent points are pre

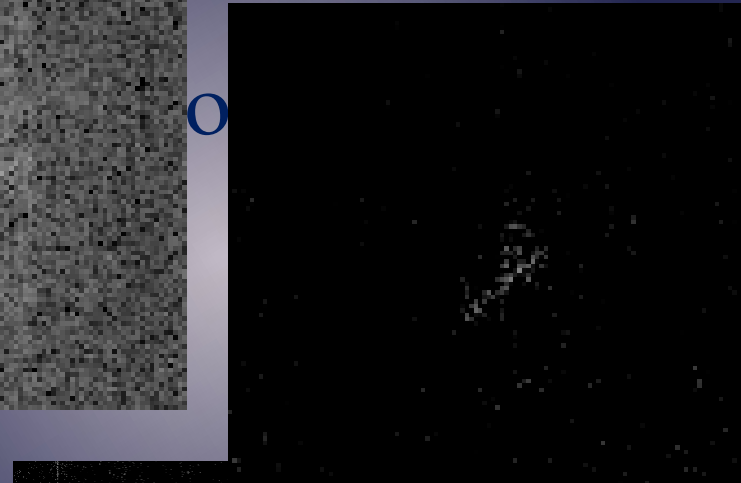


fully sampled reference  
with tank

Tank



back projection @25%  
Nyquist



CS reconstruction @25% Nyquist  
(coherent only)



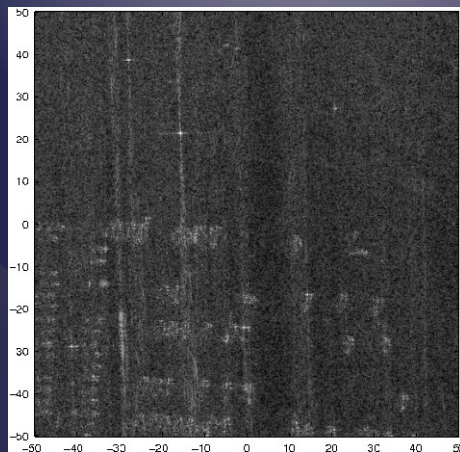
## SAR image auto focus

An added complication is estimating the propagation delay for each radar return. This introduces a phase error. Traditional auto focus techniques (e.g. Phase Gradient Autofocus) indirectly use sparsity.

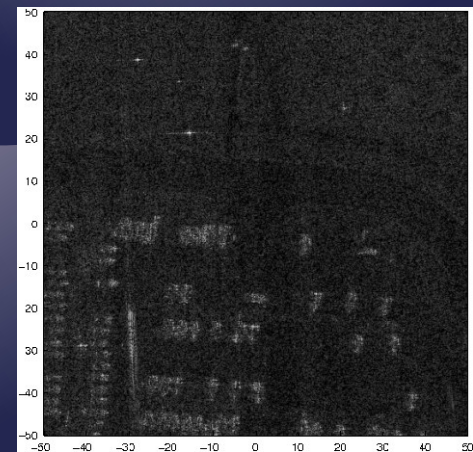
Here we can be explicit:

$$\{\theta, x^*\} = \min_{\{\phi, x\}} \|x\|_1 + \gamma \|y - \text{diag}(e^{i\phi})Ax\|_2^2 \leq \lambda$$

w/o auto focus



with auto focus



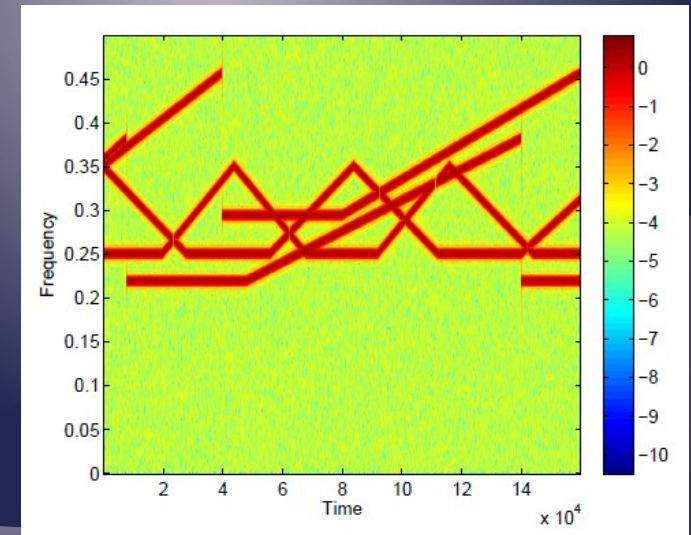
# Sparsity for Signal Detection & Separation

# Signal Separation in Electronic Surveillance

Aim: detect and separate out target waveforms in Electronic surveillance

- ∅ e.g. mixture of multiple FMCW waveforms.
- ∅ Need processing to be fast
- ∅ Want to exploit sparsity in TF domain (redundant chirplet transform)

$$C[n,k,c] = \sum_{m=-\frac{M-1}{2}}^{\frac{M-1}{2}} x[n+m]\phi[m] e^{j2\pi\frac{c}{2}m^2} e^{-j2\pi m\frac{k}{K}}$$





## Sparsity & Time-frequency masking

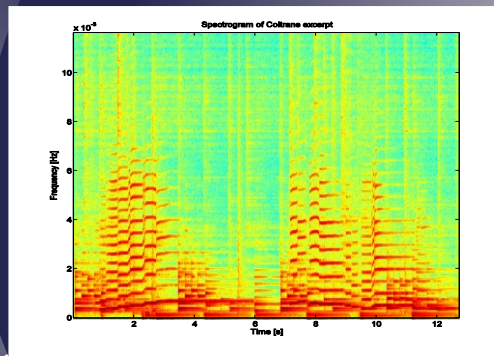
An efficient popular method for source separation in the TF domain is to use TF masking

- ∅ If signals are TF-sparse each coefficient typically dominated by a single source
- ∅ Sources can be reconstructed from groups of associated TF atoms

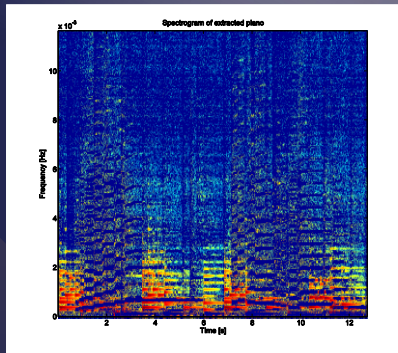


# Stereo audio separation by TF masking

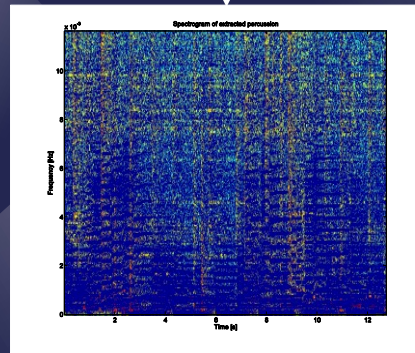
Example of source separation based on TF masking. Sources groups based on direction of arrival.



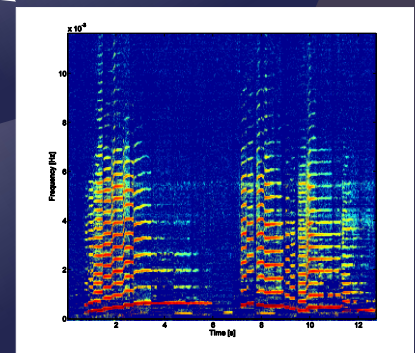
piano



percussion



sax



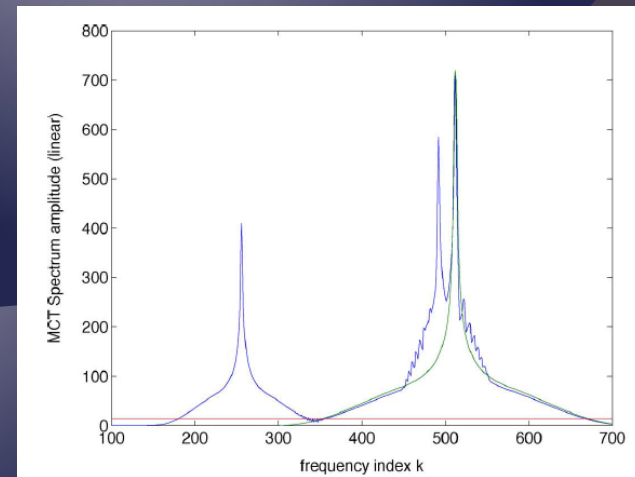
## Iterative masking

Adapt masking to redundant transforms... but still only use a single chirplet transform

1. Calculate Maximum Chirplet Transform
2. Define noise threshold (Neyman-Pearson detection)
3. **While** coefficients above threshold:
  1. Select maximum coefficient
  2. Subtract the upper-bound spectral window

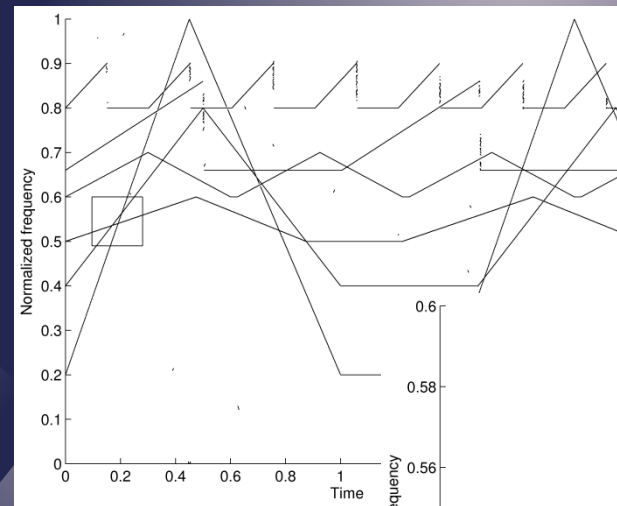
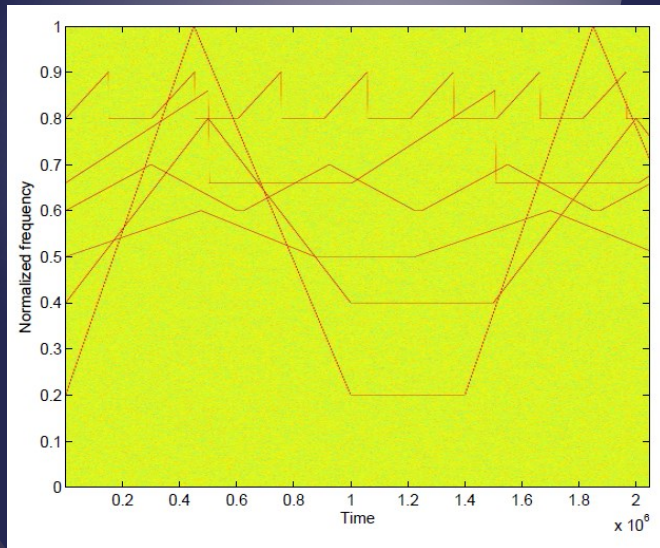
**end**

4. Group coefficients into chirps

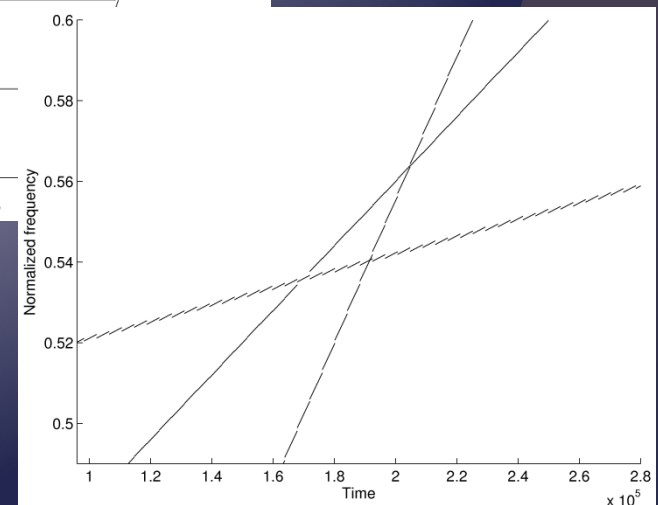


# Recovered TF Representation

Recovered components: better coherent gain than STFT



zoomed section





## Future perspectives

### Further applications in SAR & ES

- ⌘ RFI suppression in SAR (SKs talk)
- ⌘ 3D SAR imaging from through single or few nonlinear flight paths
- ⌘ Combined SAR + GMTI
- ⌘ Target classification exploiting non-isotropic scattering & spectral dependencies
- ⌘ Wideband sensing through subNyquist sampling (MYs talk)



Questions?

## Other Potential Defence applications

Sparsity is being investigated in a wide range of applications of interest to defence, including:

- ↳ Multispectral/Lidar imaging
- ↳ Blind Sensor Calibration
- ↳ Machine Learning (robust classification/estimation)
- ↳ Novel Computation (randomized linear algebra...fast matrix multiplication/SVD/etc.)

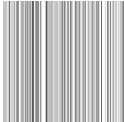

# Compressive target classification



Tank

fully sampled reference  
with tank

ATR PERFORMANCE OF DIFFERENT SCENARIOS ( $Pr_{cc}$ )

missing data pattern	data amount	CS-framework	back-projection
	full data	96.5%	95.5%
 random	25% data	93%	85.5%
	10% data	83%	69%
 gap	25% data	82%	64%
	10% data	57%	40.5%