Advanced Radar Signal Processing & Information Extraction

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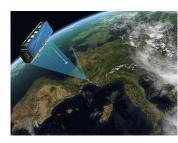
- ****** UDRC Affiliated
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Presentation Overview

- Radar Signal Processing Challenges
- Signal Processing Methods
- Signal Processing Solutions for
 - > SAR
 - Monopulse Radar Processors
 - Bistatic SAR Microdoppler Signal Analysis
- > Moving Forward within the UDRC II

Radar Signal Processing Challenges

SAR Processing:-*High Resolution SAR, MSAR, BistaticSAR*



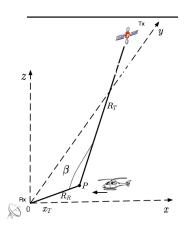


 $-\Delta(Az)$

 $+\Delta(Az)$

Monopulse Radar:-*Tgt Tracking Anti-Jamming Clutter Rejection*

> Microdoppler Analysis:-*Tgt Identification*



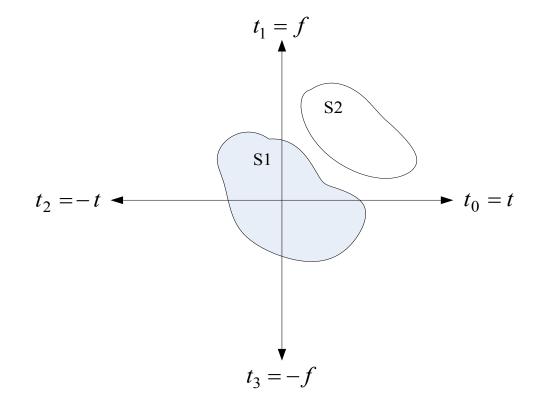
Signal Processing Methods

Fractional Fourier Transform (FrFT) 1994-optics

Empirical Mode Decomposition (EMD) 1998-Seismology

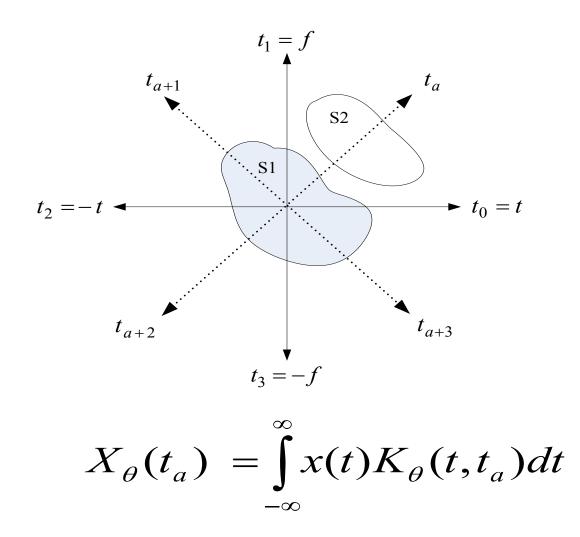
Singular Spectrum Analysis (SSA) 1997-Climatology

Fractional Fourier Transform (FrFT)

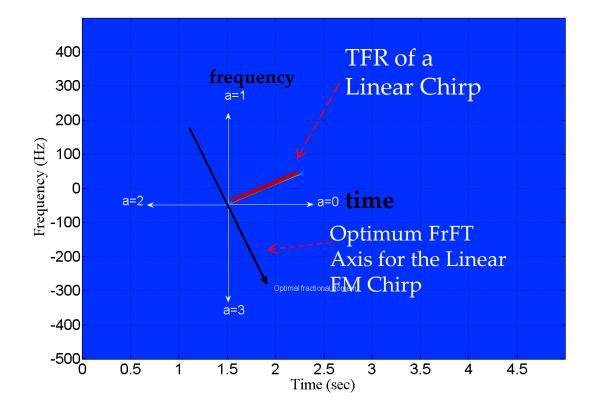


Fractional Fourier Transform (FrFT)

Almeida L, IEEE Trans SP, 1994



Fractional Fourier Transform (FrFT)

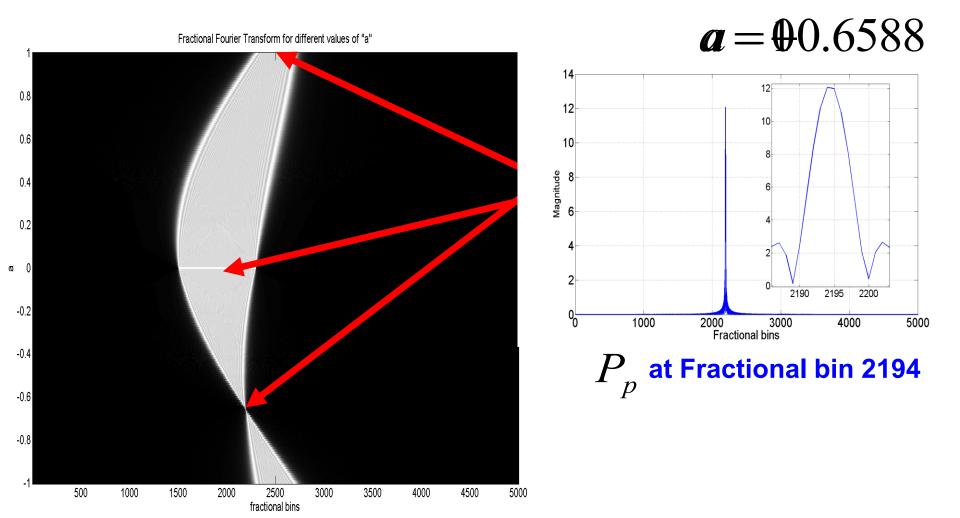


The optimum FrFT order of linear FM chirp

$$a_{opt} = -\frac{2}{\pi} \tan^{-1}\left(\frac{F_s^- \times T}{(F_{stop} - F_{start}) \times L}\right)$$

Fractional Fourier Transform

For a linear chirp with starting frequency of 5 Hz, ending frequency of 100 Hz, chirp period of 0.8 s, and sampling frequency of 1 kHz; the time window 5 s, and the chirp start at 1.5 s

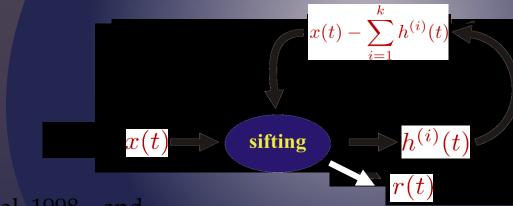


Empirical mode decomposition (EMD)

•Empirical: EMD lacks theoretical foundations.

 Mode: Intrinsic Mode Functions (IMF's) - Represents the oscillation modes embedded in the data.

-Decomposition:
$$x(t) = \sum_{i=1}^{N} h^{(i)}(t) + r(t)$$



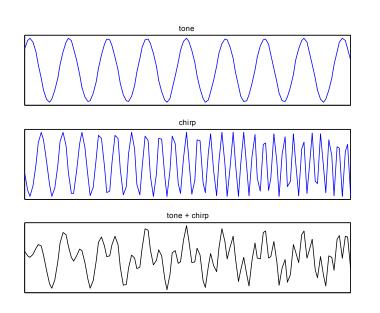
*Huang et al, 1998 and

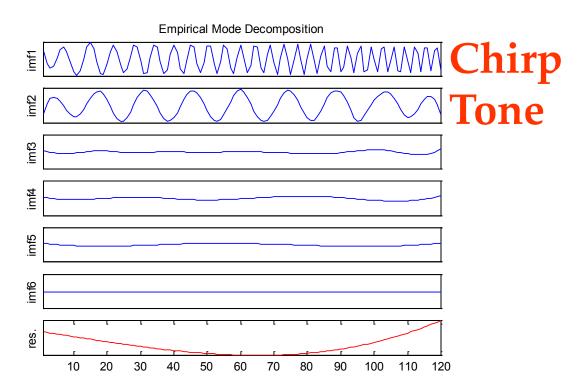
* Rilling et al , IEEE-EURASIP Workshop NSIP, June 2003



EMD Example

Example: Tone + Chirp







Methodology: (EMD noise filtering)

		IMF 1 IMF 2	Estimates the noise level in each IMF using a threshold				
Noisy EMD		IMF 3 IMF 4	Mostly noise	$T_r[i]$	=C	$W[i]2\ln($	$\overline{(N)}$
signal	Algorithm	IMF 5			C		
		IMF 7	↑	IMF 7	IMF 7	IMF 7 +	
		IMF 8	Mostly	IMF 8	IMF 8	IMF 8 +	Filtered signal
	IMF 9 IMF 10	signal	IMF 9 IMF 10	IMF 9 IMF 10	IMF 9 +		
			7			IMF 10	

Singular Spectrum Analysis (SSA)

(Hassani, H, SSA: methodolgy and comparison, 2007)

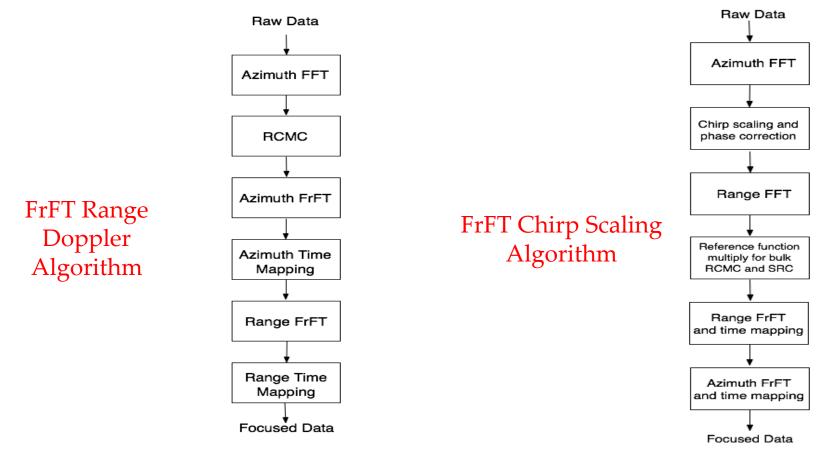
SSA is the application of SVD/PCA to time series

Summary of what it does

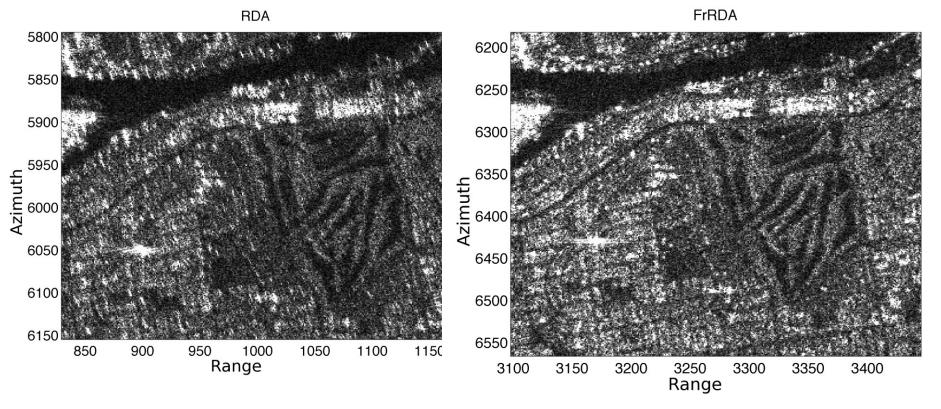
- > application of PCA to time series which is structured (embedded) into overlapping moving windows of data
- the data vectors are fragments of time series rather than spatial distributions of values at a single time
- the eigenvectors therefore represent characteristic time patterns, rather than characteristic spatial patterns
- used mainly to identify oscillatory features in the time series and in our work for Micro-Doppler Analysis

Signal Processing Solutions for

High Resolution SAR Signal Processing



Golf course area processed with the RDA and the FrRDA.

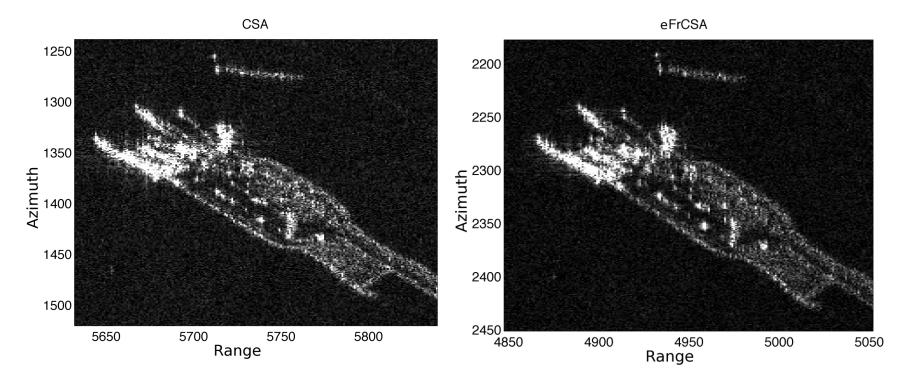


Clemente et al "Range Doppler SAR processing Using the FrFT", International Radar Symposium-IRS2010, 2010

Clemente et al ,"Fractional RDA and Enhanced FrCSA for SAR Imaging", SSPD-2010, 2010

Clemente et al ,"*Fractional Range Doppler Algorithm for SAR Imaging*", European Radar Conference, Eurad-2010, 2010

Portion of the Vancouver Tsawwassen ferry terminal area processed with the CSA and the eFrCSA.

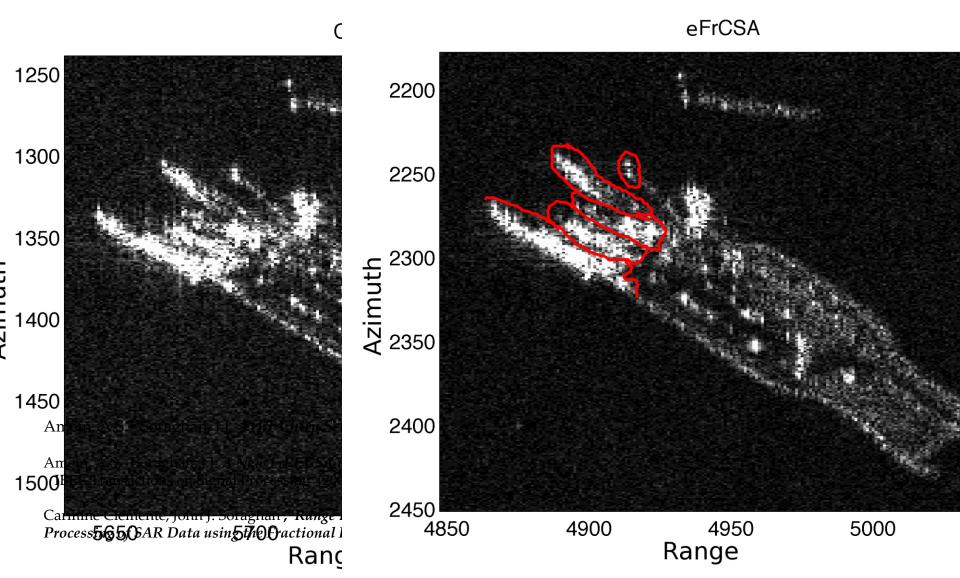


Amein, A.S. Soraghan, J.J. FrFT Chirp Scaling Algorithm (FrCSA) IEEE TGRS (2006)

Carmine Clemente, John J. Soraghan ,"Range Doppler and Chirp Scaling Processing of SAR Data using the Fractional Fourier Transform", IET Signal Processing (2010).

Amein, A.S. Soraghan, J.J. *A New FrFT CSA with Application to High Resolution Radar Imaging* IEEE Transactions on Signal Processing (2007)

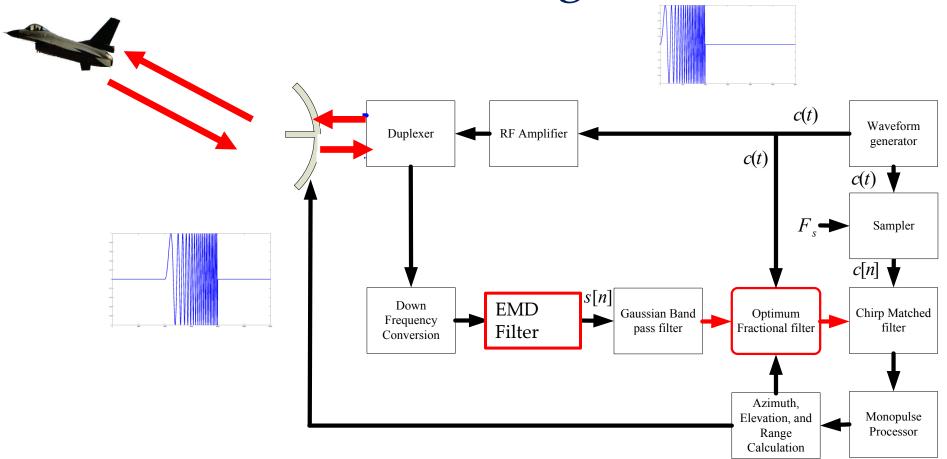
Portion of the Vancouver Tsawwassen ferry terminal area processed with the CSA and the eFrCSA.



Signal Processing Solutions for

Target Tracking & Anti-Jamming

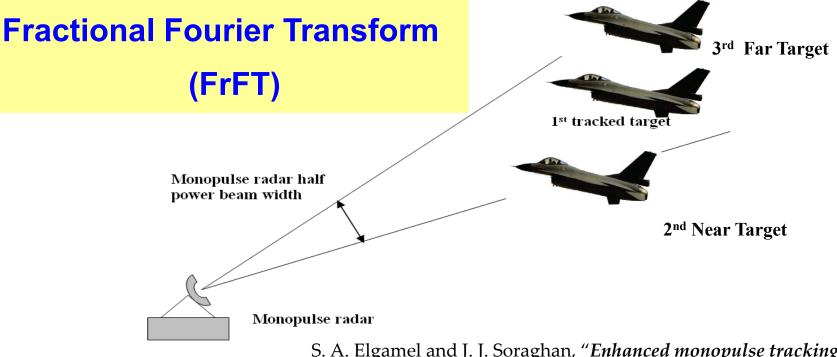
FrFT/EMD Monopulse Radar Tracking



[A] Tracking

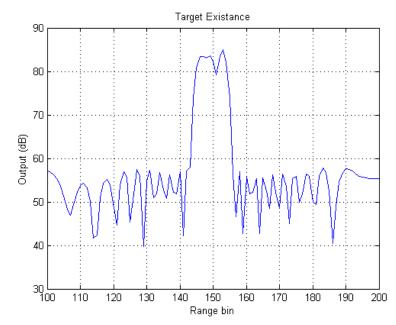
Solve the problem of interference due to more than one target appearing in the monopulse radar half power beam width

three targets scenario for Monopulse radar



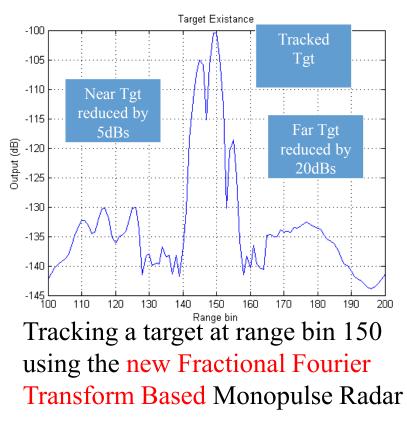
S. A. Elgamel and J. J. Soraghan, *"Enhanced monopulse tracking radar using optimum Fractional Fourier Transform,*" IET Journal of Radar, Sonar & Navigation, July 2010.

Results from the Fractional Fourier Transform based Monopulse Radar System



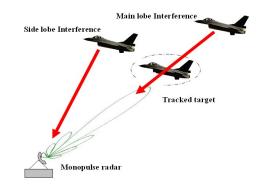
Tracking a target at range bin 150 using convenional Spatial Adaptive Monopulse Radar

➔ Poor Tracking Result

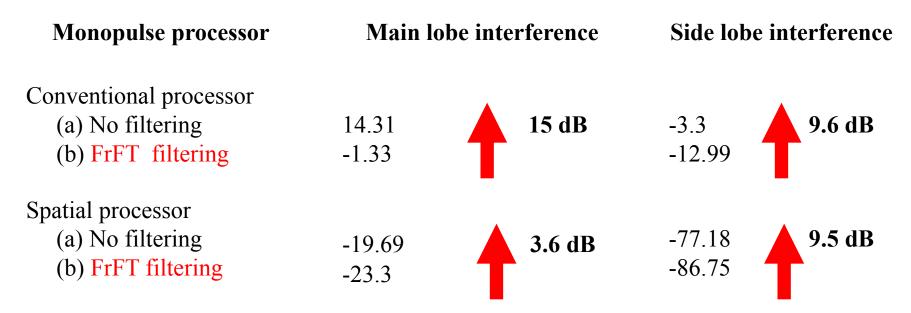


→ Tracking of main target maintained

Results :(High power interference)



OINR in db for Monopulse Processors



[B] High Power Jamming Interference

Tracked target

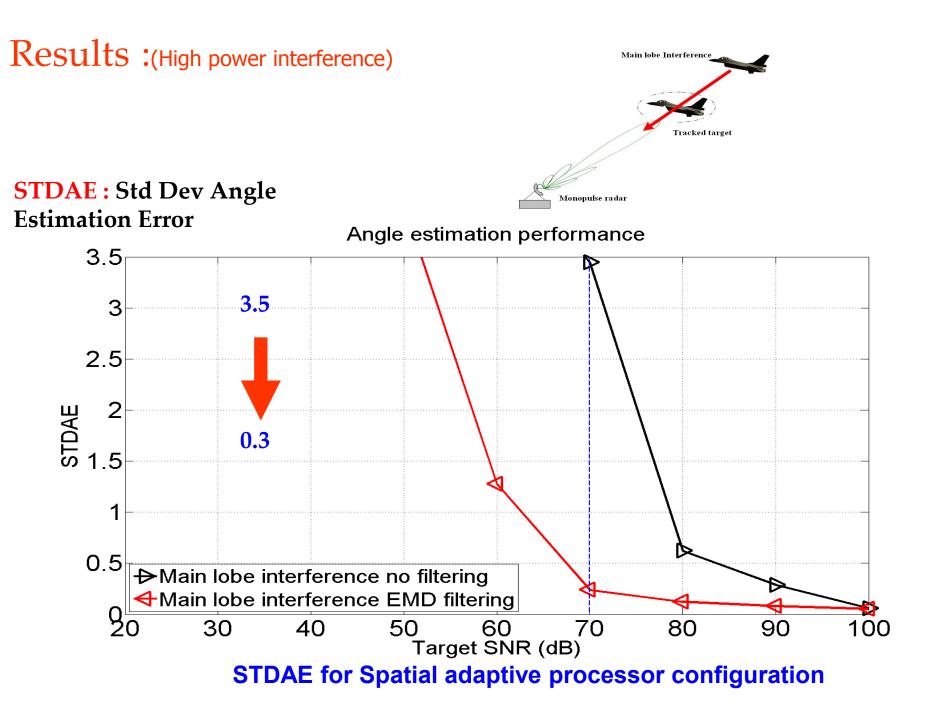
Fractional Fourier Transform
Empirical Mode decomposition

Monopulse radar

Interference scenarios for Monopulse radar.

Elgamel & Soraghan, "*Empirical mode decomposition-based monopulse processor for enhanced radar tracking in the presence of high-power interference*" IET Radar, Sonar & Navigation, August 2011

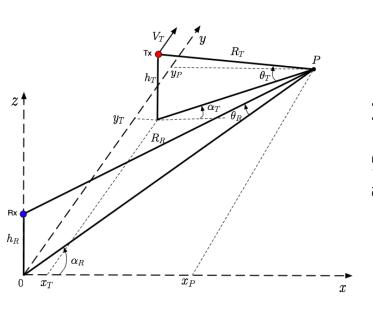
Elgamel, S.A.; Soraghan, J.J.; *Using EMD-FrFT Filtering to Mitigate Very High Power Interference in Chirp Tracking Radars,* IEEE Signal Processing Letters. Volume: 18, 2011, Page(s): 263 - 266

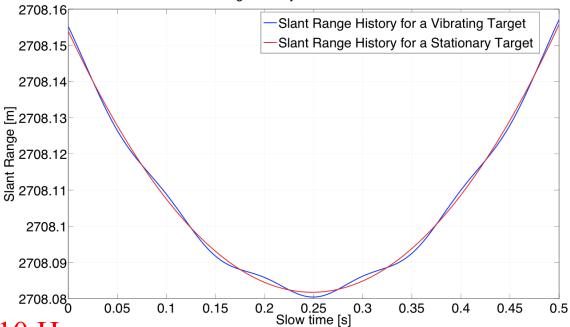


Signal Processing Solutions for

Microdoppler Signature Extraction from BiSAR

Bistatic SAR Geometry





Slant Range History with and without vibration

A small 1 mm amplitude at 10 Hz introduces a visible effect on the bistatic slant range function

Clemente et al ,"*Vibrating Target Micro-Doppler Signature in Bistatic SAR with a Fixed Receiver*", IEEE Trans on Geoscience and Remote Sensing, August 2012 Clemente et al ,"*Approximation of the Bistatic Slant Range Using Chebyshev Polynomials*", IEEE Trans Geoscience and Remote Sensing Letters, July 2012

Helicopters

Table: Simulated helicopters and rotor blades features.

Model	# of	Blade	Blade
	blades	length [m]	width [m]
AW-109 Agusta	4	5.5	0.6
AH-64 Apache	4	7.3	0.6
UH-60 Black Hawk	4	8.18	0.6
MD 500E Defender	5	4	0.6

Table: Tip velocity, expected maximum micro-Doppler shift and RCS

Model	Тір	Maximum	RCS
	Velocity [m/s]	m-D shift [Hz]	[dBsm]
AW-109 Agusta	241.90	112.24	25.76
AH-64 Apache	220.16	102.13	28.2
UH-60 Black Hawk	221.00	102.52	29.2
MD 500E Defender	206.08	95.60	22.9

Helicopters

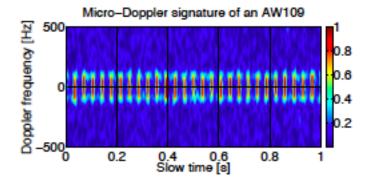


Figure: AW109.

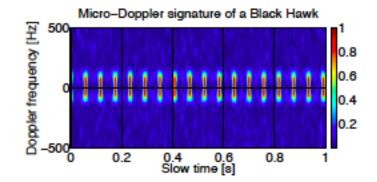


Figure: Black Hawk.

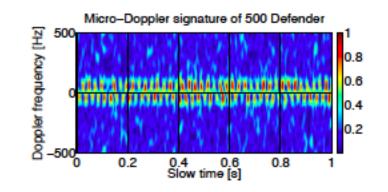


Figure: Defender.

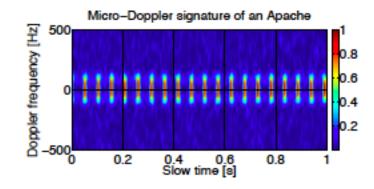


Figure: Apache.

Micro-Doppler Signal Extraction in clutter

- Strong Clutter can mask micro-Doppler signatures
 - ➢ In SAR the surrounding scene produces strong clutter
 - The fuselage of a helicopter and the direct signal will produce strong signals to the receiver
- Singular Spectrum Analysis (SSA) based methods have been developed and applied in low SCR micro-Doppler

Carmine Clemente, John J. Soraghan,"*Vibrating Micro-Doppler signature extraction from SAR data using Singular Value Decomposition*", EUSAR2012, European Conference on Synthetic Aperture Radar, 2012

Extraction from clutter

SSA applied to extract helicopter rotor blades signatures with a Signal-to-Clutter and Interference Ratio less than -90 dB.

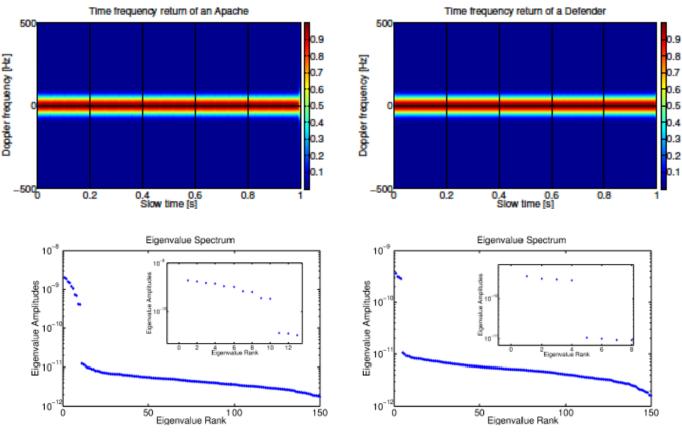


Figure: Results for an Apache and a Defender

Extraction from clutter

We applied the technique to the helicopter rotor blades signatures with a Signal to Clutter and Interference Ratio less than -90 dB.

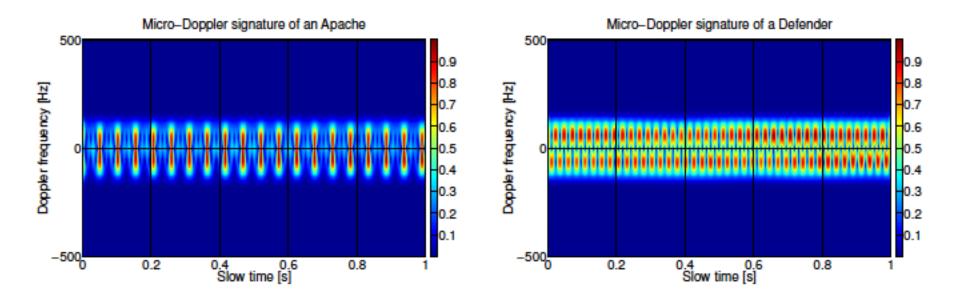


Figure: Results for an Apache and a Defender

Carmine Clemente, John J. Soraghan, "*Passive Bistatic Radar for Helicopters Classication: a Feasibility Study*", IEEE Radar Conference 2012, Radarconf2012, May 7-11, Atlanta, USA

Moving Forward within the UDRC

> MIMO & Distributed Sensing Systems

- Waveform Design
- Micro-Doppler for ATR

 FrFT/EMD/LBP based Solutions for Sonar

Questions ?